

A VISCOSITY NONLINEAR MIDPOINT ALGORITHM FOR NONEXPANSIVE SEMIGROUP

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ABSTRACT. In this paper, we propose a viscosity nonlinear midpoint algorithm (VNMA) for finding a solution of fixed point problem for a nonexpansive semigroup in real Hilbert spaces. Under certain conditions control on parameters, the iteration sequences generated by the proposed algorithm are proved to be strongly convergent to a solution of fixed point problem for a nonexpansive semigroup. Some numerical examples are presented to illustrate the convergence result. Our results improve and extend the corresponding results in the literature.

KEYWORDS: Nonexpansive semigroup, Equilibrium problem, Midpoint method, Strongly positive linear bounded operator, Fixed point, Hilbert space.

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1. INTRODUCTION

The explicit midpoint rule is one of the powerful numerical methods for solving ordinary differential equations and differential algebraic equations. For related works, we refer to [2, 3, 4, 7, 8, 14, 17, 16] and the references cited therein. For instance, consider the initial value problem for the differential equation $y'(t) = f(y(t))$ with the initial condition $y(0) = y_0$, where f is a continuous function from \mathbb{R}^d to \mathbb{R}^d . The explicit midpoint rule which generates a sequence $\{y_n\}$ by following the recurrence relation

$$\frac{1}{h}(y_{n+1} - y_n) = f\left(\frac{y_{n+1} + y_n}{2}\right).$$

In 2015, Xu et al. [19] extended and generalized the results of Alghamdi et al. [1] and applied the viscosity method on the midpoint rule for nonexpansive mappings and they give the generalized viscosity explicit method:

$$x_{n+1} = \alpha_n f(x_n) + \beta_n x_n + (1 - \alpha_n) T\left(\frac{x_n + x_{n+1}}{2}\right).$$

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In 2016, Rizvi [13] introduced the following iterative method for the explicit midpoint rule of nonexpansive mappings:

$$x_{n+1} = \alpha_n \gamma f(x_n) + (1 - \alpha_n B)T\left(\frac{x_n + x_{n+1}}{2}\right).$$

Motivated and inspired by the results mentioned and related literature in [1, 13, 19], we propose an iterative midpoint algorithm based on the viscosity method for finding a common element of the set of solutions of nonexpansive semigroup in Hilbert spaces. Then we prove strong convergence theorems that extend and improve the corresponding results of Rizvi [13], Xu [19], and others. Finally, we give examples and numerical result to illustrate our main result.

The rest of paper is organized as follows. The next section presents some preliminary results. Section 3 is devoted to introduce midpoint algorithm for solving it. The last section presents a numerical example to demonstrate the proposed algorithms.

2. PRELIMINARIES

Let \mathbb{R} denote the set of all real numbers, H be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and norm $\|\cdot\|$ and C be a nonempty closed convex subset of H .

A mapping $T : C \rightarrow C$ is said to be a contraction if there exists a constant $\alpha \in (0, 1)$ such that $\|T(x) - T(y)\| \leq \alpha \|x - y\|$, for all $x, y \in C$. If $\alpha = 1$ then T is called nonexpansive on C .

The fixed point problem (FPP) for a nonexpansive mapping T is: To find $x \in C$ such that $x \in \text{Fix}(T)$, where $\text{Fix}(T)$ is the fixed point set of the nonexpansive mapping T .

In 2006, Marino and Xu [11] considered the following iterative method:

$$x_{n+1} = \alpha_n \gamma f(x_n) + (I - \alpha_n B)Tx_n$$

with $0 < \gamma < \frac{\bar{\gamma}}{\alpha}$ and prove that the sequence $\{x_n\}$ converges strongly to the unique solution of the variational inequality $\langle (B - \gamma f)z, x - z \rangle \geq 0, \forall x \in \text{Fix}(T)$ which is the optimality condition for minimization problem

$$\min_{x \in \text{Fix}(T)} \frac{1}{2} \langle Bx, x \rangle - h(x)$$

where h is the potential function for γf and $B : H \rightarrow H$ is a strongly positive linear bounded operator, i.e., if there exists a constant $\bar{\gamma} > 0$ such that $\langle Bx, x \rangle \geq \bar{\gamma} \|x\|^2, \forall x \in \text{Fix}(T)$.

A family $S := \{T(s) : 0 \leq s < \infty\}$ of mappings from C into itself is called a nonexpansive semigroup on C if it satisfies the following conditions:

- (i) $T(0)x = x$ for all $x \in C$
- (ii) $T(s+t) = T(s)T(t)$ for all $s, t \geq 0$
- (iii) $\|T(s)x - T(s)y\| \leq \|x - y\|$ for all $x, y \in C$ and $s \geq 0$
- (iv) For all $x \in C, s \rightarrow T(s)x$ is continuous.

Chen and Song [6] introduced and studied the following iterative method to prove a strong convergence theorem for FPP in a real Hilbert space:

$$x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n) \frac{1}{s_n} \int_0^{s_n} T(s)x_n ds.$$

where f is a contraction mapping. For each point $x \in H$, there exists a unique nearest point of C , denote by $P_C x$, such that $\|x - P_C x\| \leq \|x - y\|$ for all $y \in C$. P_C

is called the metric projection of H onto C . It is well known that P_C is nonexpansive mapping and is characterized by the following property:

$$\langle x - P_C x, y - P_C y \rangle \leq 0 \quad (2.1)$$

Further, it is well known that every nonexpansive operator $T : H \rightarrow H$ satisfies, for all $(x, y) \in H \times H$, inequality

$$\langle (x - T(x)) - (y - T(y)), T(y) - T(x) \rangle \leq \left(\frac{1}{2}\right) \|(T(x) - x) - (T(y) - y)\|^2. \quad (2.2)$$

It is also known that H satisfies Opial's condition [12], i.e., for any sequence $\{x_n\}$ with $x_n \rightharpoonup x$, the inequality

$$\liminf_{n \rightarrow \infty} \|x_n - x\| < \liminf_{n \rightarrow \infty} \|x_n - y\| \quad (2.3)$$

holds for every $y \in H$ with $y \neq x$.

Lemma 2.1. [5] *The following inequality holds in real space H :*

$$\|x + y\|^2 \leq \|x\|^2 + 2\langle y, x + y \rangle, \quad \forall x, y \in H.$$

Definition 2.2. A mapping $M : C \rightarrow H$ is said to be monotone, if

$$\langle Mx - My, x - y \rangle \geq 0, \quad \forall x, y \in C.$$

M is called α -inverse-strongly-monotone if there exists a positive real number α such that

$$\langle Mx - My, x - y \rangle \geq \alpha \|Mx - My\|^2, \quad \forall x, y \in C.$$

Lemma 2.3. [11] *Assume that B is a strong positive linear bounded self adjoint operator on a Hilbert space H with coefficient $\bar{\gamma} > 0$ and $0 < \rho \leq \|B\|^{-1}$. Then $\|I - \rho B\| \leq 1 - \rho \bar{\gamma}$.*

Lemma 2.4. [15] *Let C be a nonempty bounded closed convex subset of a Hilbert space H and let $S := \{T(s) : 0 \leq s < \infty\}$ be a nonexpansive semigroup on C , for each $x \in C$ and $t > 0$. Then, for any $0 \leq h < \infty$,*

$$\lim_{t \rightarrow \infty} \sup_{x \in C} \left\| \frac{1}{t} \int_0^t T(s)x ds - T(h) \left(\frac{1}{t} \int_0^t T(s)x ds \right) \right\| = 0.$$

Lemma 2.5. [18] *Let $\{a_n\}$ be a sequence of nonnegative real numbers such that $a_{n+1} \leq (1 - \alpha_n)a_n + \delta_n$, $n \geq 0$ where α_n is a sequence in $(0, 1)$ and δ_n is a sequence in \mathbb{R} such that*

$$(i) \sum_{n=1}^{\infty} \alpha_n = \infty; \quad (ii) \limsup_{n \rightarrow \infty} \frac{\delta_n}{\alpha_n} \leq 0 \quad \text{or} \quad \sum_{n=1}^{\infty} \delta_n < \infty.$$

Then $\lim_{n \rightarrow \infty} a_n = 0$.

3. Viscosity Nonlinear Midpoint Algorithm

In this section, we prove a strong convergence theorem based on the explicit iterative for fixed point of nonexpansive semigroup. We firstly present the following unified algorithm.

Let C be a nonempty closed convex subset of real Hilbert space H . Let $S = \{T(s) : s \in [0, +\infty)\}$ be a nonexpansive semigroup on C such that $\text{Fix}(S) \neq \emptyset$. Also $f : C \rightarrow H$ be a α -contraction mapping and A be a strongly positive bounded linear self adjoint operator on H with coefficient $\bar{\gamma} > 0$ such that $0 < \gamma < \frac{\bar{\gamma}}{\alpha} < \gamma + \frac{1}{\alpha}$ and $\bar{\gamma} \leq \|A\| \leq 1$.

Algorithm 3.1. For given $x_0 \in C$ arbitrary, let the sequence $\{x_n\}$ be generated by:

$$x_{n+1} = \alpha_n \gamma f(x_n) + (1 - \alpha_n A) \frac{1}{s_n} \int_0^{s_n} T(s) \left(\frac{x_n + x_{n+1}}{2} \right) ds. \quad (3.1)$$

where $\{\alpha_n\}$ is a sequence in $(0, 1)$ and $\{s_n\} \subset [s, \infty)$ with $s > 0$ satisfying conditions:

- (C1) $\lim_{n \rightarrow \infty} \alpha_n = 0$, $\sum_{n=1}^{\infty} \alpha_n = \infty$;
 (C2) $\sum_{n=1}^{\infty} |\alpha_n - \alpha_{n-1}| < \infty$ or $\lim_{n \rightarrow \infty} \frac{\alpha_{n+1}}{\alpha_n} = 1$;
 (C3) $\lim_{n \rightarrow \infty} s_n = \infty$, $\sup_{n \in \mathbb{N}} |s_{n+1} - s_n|$ is bounded.

In the next remark, we observe that the iterative Algorithm 3.1 is well defined for all n .

Remark 3.2. For all $t \in (0, \|A\|^{-1})$ and $u \in C$ fixed, the mapping

$$x \mapsto V_t x := t\gamma f(u) + (1 - tA) \frac{1}{s_n} \int_0^{s_n} T(s) \left(\frac{u + x}{2} \right) ds$$

is a contraction with coefficient $\frac{1}{2}(1 - t\bar{\gamma}) \in (0, 1)$. This is immediately clear, due to the nonexpansivity semigroup of $S = \{T(s) : s \in [0, +\infty)\}$ and the inequality (2.3). In fact, we have, for all $x, y \in H$,

$$\begin{aligned} \|V_t x - V_t y\| &= \|t\gamma f(u) + (1 - tA) \frac{1}{s_n} \int_0^{s_n} T(s) \left(\frac{u+x}{2} \right) ds - t\gamma f(u) - (1 - tA) \frac{1}{s_n} \int_0^{s_n} T(s) \left(\frac{u+y}{2} \right) ds\| \\ &\leq (1 - t\bar{\gamma}) \frac{1}{s_n} \int_0^{s_n} \|T(s) \left(\frac{u+x}{2} \right) ds - T(s) \left(\frac{u+y}{2} \right) ds\| \\ &\leq \frac{1}{2}(1 - t\bar{\gamma}) \|x - y\|. \end{aligned}$$

Hence the Algorithm 3.1 is well defined. Moreover, V_t has a unique fixed point, denoted by x_t , which uniquely solves the fixed point equation

$$x_t = t\gamma f(u) + (1 - tA) \frac{1}{s_n} \int_0^{s_n} T(s) \left(\frac{u + x_t}{2} \right) ds. \quad (3.2)$$

Lemma 3.3. Let $p \in \text{Fix}(S)$. Then the sequence $\{x_n\}$ generated by Algorithm 3.1 is bounded.

Proof. Let $p \in \text{Fix}(S)$, we obtain

$$\begin{aligned} \|x_{n+1} - p\| &= \|\alpha_n \gamma f(x_n) + (1 - \alpha_n A) \frac{1}{s_n} \int_0^{s_n} T(s) \left(\frac{x_n + x_{n+1}}{2} \right) ds - p\| \\ &\leq \alpha_n \|\gamma f(x_n) - Ap\| + (1 - \alpha_n \bar{\gamma}) \left\| \frac{1}{s_n} \int_0^{s_n} T(s) \left(\frac{x_n + x_{n+1}}{2} \right) - T(s)p \right\| ds \\ &\leq \alpha_n (\|\gamma f(x_n) - \gamma f(p)\| + \|\gamma f(p) - Ap\|) + (1 - \alpha_n \bar{\gamma}) \left\| \frac{x_n + x_{n+1}}{2} - p \right\| \\ &\leq \alpha_n \gamma \alpha \|x_n - p\| + \alpha_n \|\gamma f(p) - Ap\| + \frac{(1 - \alpha_n \bar{\gamma})}{2} (\|x_n - p\| + \|x_{n+1} - p\|). \end{aligned}$$

which implies that

$$\frac{1 + \alpha_n \bar{\gamma}}{2} \|x_{n+1} - p\| \leq (\alpha_n \gamma \alpha + \frac{1 - \alpha_n \bar{\gamma}}{2}) \|x_n - p\| + \alpha_n \|\gamma f(p) - Ap\|.$$

Then

$$\begin{aligned}
\|x_{n+1} - p\| &\leq \left(1 - \frac{2(\bar{\gamma} - \gamma\alpha)\alpha_n}{1 + \alpha_n\bar{\gamma}}\right)\|x_n - p\| + \frac{2\alpha_n(\bar{\gamma} - \gamma\alpha)}{1 + \alpha_n\bar{\gamma}} \frac{\|\gamma f(p) - Ap\|}{\bar{\gamma} - \gamma\alpha} \\
&\leq \max\{\|x_n - p\|, \frac{\|\gamma f(p) - Ap\|}{\bar{\gamma} - \gamma\alpha}\} \\
&\quad \vdots \\
&\leq \max\{\|x_0 - p\|, \frac{\|\gamma f(p) - Ap\|}{\bar{\gamma} - \gamma\alpha}\}.
\end{aligned} \tag{3.3}$$

Hence $\{x_n\}$ is bounded. \square

Now, set $t_n := \frac{1}{s_n} \int_0^{s_n} T(s) \left(\frac{x_n + x_{n+1}}{2}\right) ds$. Then $\{t_n\}$ and $\{f(x_n)\}$ are bounded.

Lemma 3.4. *The following properties are satisfying for the Algorithm 3.1*

$$P1. \quad \lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = 0.$$

$$P2. \quad \lim_{n \rightarrow \infty} \|x_n - t_n\| = 0.$$

$$P3. \quad \lim_{n \rightarrow \infty} \|T(s)t_n - t_n\| = 0.$$

Proof. P1: Let $p \in \text{Fix}(S)$, we have,

$$\begin{aligned}
&\|t_{n+1} - t_n\| \\
&= \left\| \frac{1}{s_{n+1}} \int_0^{s_{n+1}} T(s) \left(\frac{x_{n+1} + x_{n+2}}{2}\right) ds - \frac{1}{s_n} \int_0^{s_n} T(s) \left(\frac{x_n + x_{n+1}}{2}\right) ds \right\| \\
&= \left\| \frac{1}{s_{n+1}} \int_0^{s_{n+1}} (T(s) \left(\frac{x_{n+1} + x_{n+2}}{2}\right) - T(s) \left(\frac{x_n + x_{n+1}}{2}\right)) ds + \left(\frac{1}{s_{n+1}} - \frac{1}{s_n}\right) \int_0^{s_n} T(s) \left(\frac{x_n + x_{n+1}}{2}\right) ds \right. \\
&\quad \left. + \frac{1}{s_{n+1}} \int_{s_n}^{s_{n+1}} T(s) \left(\frac{x_n + x_{n+1}}{2}\right) ds \right\| \\
&= \left\| \frac{1}{s_{n+1}} \int_0^{s_{n+1}} (T(s) \left(\frac{x_{n+1} + x_{n+2}}{2}\right) - T(s) \left(\frac{x_n + x_{n+1}}{2}\right)) ds \right. \\
&\quad \left. + \left(\frac{1}{s_{n+1}} - \frac{1}{s_n}\right) \int_0^{s_n} (T(s) \left(\frac{x_n + x_{n+1}}{2}\right) - T(s)p) ds + \frac{1}{s_{n+1}} \int_{s_n}^{s_{n+1}} (T(s) \left(\frac{x_n + x_{n+1}}{2}\right) - T(s)p) ds \right\| \\
&\leq \left\| \frac{x_{n+1} + x_{n+2}}{2} - \frac{x_n + x_{n+1}}{2} \right\| + \frac{|s_{n+1} - s_n| s_n}{s_{n+1} s_n} \left\| \frac{x_n + x_{n+1}}{2} - p \right\| + \frac{|s_{n+1} - s_n|}{s_{n+1}} \left\| \frac{x_n + x_{n+1}}{2} - p \right\| \\
&\leq \frac{1}{2} (\|x_{n+1} - x_n\| + \|x_{n+2} - x_{n+1}\|) + \frac{|s_{n+1} - s_n|}{s_{n+1}} (\|x_n - p\| + \|x_{n+1} - p\|).
\end{aligned} \tag{3.4}$$

Next, we show that the sequence $\{x_n\}$ is asymptotically regular, i.e.,

$$\lim_{n \rightarrow \infty} \|x_{n+2} - x_{n+1}\| = 0.$$

By (3.4) we estimate that

$$\begin{aligned}
& \|x_{n+2} - x_{n+1}\| \\
&= \|(\alpha_{n+1}\gamma f(x_{n+1}) + (1 - \alpha_{n+1}A)\frac{1}{s_{n+1}} \int_0^{s_{n+1}} T(s)(\frac{x_{n+1}+x_{n+2}}{2})ds) \\
&\quad - (\alpha_n\gamma f(x_n) + (1 - \alpha_nA)\frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n+x_{n+1}}{2})ds)\| \\
&= \|(1 - \alpha_{n+1}A)(\frac{1}{s_{n+1}} \int_0^{s_{n+1}} T(s)(\frac{x_{n+1}+x_{n+2}}{2})ds - \frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n+x_{n+1}}{2})ds) \\
&\quad + (\alpha_nA - \alpha_{n+1}A)\frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n+x_{n+1}}{2})ds + (\alpha_{n+1} - \alpha_n)\gamma f(x_n) \\
&\quad + \alpha_{n+1}(\gamma f(x_{n+1}) - \gamma f(x_n))\| \\
&\leq (1 - \alpha_{n+1}\bar{\gamma})\|t_{n+1} - t_n\| + M|\alpha_n - \alpha_{n+1}| + \alpha_{n+1}\gamma\|f(x_{n+1}) - f(x_n)\| \\
&\leq (1 - \alpha_{n+1}\bar{\gamma})\|t_{n+1} - t_n\| + M|\alpha_n - \alpha_{n+1}| + \alpha_{n+1}\gamma\alpha\|x_{n+1} - x_n\| \\
&\leq \frac{1 - \alpha_{n+1}\bar{\gamma}}{2}(\|x_{n+1} - x_n\| + \|x_{n+2} - x_{n+1}\|) + (1 - \alpha_{n+1}\bar{\gamma})\frac{|s_{n+1} - s_n|}{s_{n+1}}(\|x_n - p\| \\
&\quad + \|x_{n+1} - p\|) + M|\alpha_n - \alpha_{n+1}| + \alpha_{n+1}\gamma\alpha\|x_{n+1} - x_n\|,
\end{aligned}$$

where $M := \sup\{\frac{1}{s_n} \int_0^{s_n} T(s)(\frac{x_n+x_{n+1}}{2})ds + \gamma\|f(x_n)\|\}$.

Then

$$\begin{aligned}
(1 + \alpha_{n+1}\bar{\gamma})\|x_{n+2} - x_{n+1}\| &\leq (1 + (2\alpha\gamma - \bar{\gamma})\alpha_{n+1})\|x_{n+1} - x_n\| \\
&\quad + (1 - \alpha_{n+1}\bar{\gamma})\frac{2|s_{n+1} - s_n|}{s_{n+1}}(\|x_n - p\| + \|x_{n+1} - p\|) \\
&\quad + 2M|\alpha_n - \alpha_{n+1}|.
\end{aligned}$$

Therefore

$$\begin{aligned}
\|x_{n+2} - x_{n+1}\| &\leq (1 - \frac{2(\bar{\gamma} - \alpha\gamma)\alpha_{n+1}}{1 + \alpha_{n+1}\bar{\gamma}})\|x_{n+1} - x_n\| + (\frac{1 - \alpha_{n+1}\bar{\gamma}}{1 + \alpha_{n+1}\bar{\gamma}})(\frac{2|s_{n+1} - s_n|}{s_{n+1}})(\|x_n - p\| \\
&\quad + \|x_{n+1} - p\|) + \frac{2M}{1 + \alpha_{n+1}\bar{\gamma}}|\alpha_n - \alpha_{n+1}|.
\end{aligned}$$

Hence, it follows by Lemma 2.5 that

$$\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = 0. \quad (3.5)$$

And similarly, we have

$$\lim_{n \rightarrow \infty} \|x_{n+2} - x_{n+1}\| = 0. \quad (3.6)$$

Also by (3.4), (3.5), (3.6) and (C3) we have $\lim_{n \rightarrow \infty} \|t_{n+1} - t_n\| = 0$.

P2: We can write

$$\begin{aligned}
\|x_n - t_n\| &\leq \|x_{n+1} - x_n\| + \|\alpha_n\gamma f(x_n) + (1 - \alpha_nA)t_n - t_n\| \\
&\leq \|x_n - x_{n+1}\| + \alpha_n\|\gamma f(x_n) - At_n\|.
\end{aligned}$$

By (C1) and (3.5), we obtain

$$\lim_{n \rightarrow \infty} \|x_n - t_n\| = 0. \quad (3.7)$$

P3: Let $K := \{w \in C : \|w - p\| \leq \|x_0 - p\|, \frac{1}{\bar{\gamma} - \gamma\alpha} \|\gamma f(p) - Bp\|\}$. Then K is a nonempty bounded closed convex subset of C which is $T(s)$ -invariant for each $s \in [0, +\infty)$ and contains $\{x_n\}$. So, without loss of generality, we may assume that $S := \{T(s) : s \in [0, +\infty)\}$ is a nonexpansive semigroup on K .

$$\begin{aligned}
\|T(s)x_n - x_n\| &= \|T(s)x_n - T(s)\frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds + T(s)\frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds \\
&\quad - \frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds + \frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds - x_n\| \\
&\leq \|T(s)x_n - T(s)\frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds\| \\
&\quad + \|T(s)\frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds - \frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds\| \\
&\quad + \|\frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds - x_n\| \\
&\leq \|x_n - \frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds\| \\
&\quad + \|T(s)\frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds - \frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds\| \\
&\quad + \|\frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds - x_n\| \\
&= 2\|\frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds - x_n\| \\
&\quad + \|T(s)\frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds - \frac{1}{s_n} \int_0^{s_n} T(s)\left(\frac{x_n+x_{n+1}}{2}\right)ds\|
\end{aligned}$$

Since $\frac{x_n+x_{n+1}}{2} \in C$, from (3.7) and Lemma 2.4, we obtain $\lim_{n \rightarrow \infty} \|T(s)x_n - x_n\| = 0$.

Therefore

$$\begin{aligned}
\|T(s)t_n - t_n\| &\leq \|T(s)t_n - T(s)x_n\| + \|T(s)x_n - x_n\| + \|x_n - t_n\| \\
&\leq \|t_n - x_n\| + \|T(s)x_n - x_n\| + \|x_n - t_n\|.
\end{aligned}$$

Then we have $\lim_{n \rightarrow \infty} \|T(s)t_n - t_n\| = 0$. \square

4. Convergence Algorithm

Theorem 4.1. *The Algorithm defined by (3.1) convergence strongly to $z \in \text{Fix}(S)$, which is a unique solution in of the variational inequality $\langle (\gamma f - A)z, y - z \rangle \leq 0$, $\forall y \in \text{Fix}(S)$.*

Proof. Let $s = P_{\text{Fix}(S)}$. We get

$$\begin{aligned}
\|s(I - A + \gamma f)(x) - s(I - A + \gamma f)(y)\| &\leq \|(I - A + \gamma f)(x) - (I - A + \gamma f)(y)\| \\
&\leq \|I - A\| \|x - y\| + \gamma \|f(x) - f(y)\| \\
&\leq (1 - \bar{\gamma}) \|x - y\| + \gamma\alpha \|x - y\| \\
&= (1 - (\bar{\gamma} - \gamma\alpha)) \|x - y\|.
\end{aligned}$$

Then $s(I - A + \gamma f)$ is a contraction mapping from H into itself. Therefore by Banach contraction principle, there exists $z \in H$ such that $z = s(I - A + \gamma f)z =$

$P_{\text{Fix}(S)}(I - A + \gamma f)z$.

We show that $\langle (\gamma f - A)z, x_n - z \rangle \leq 0$. To show this inequality, we choose a subsequence $\{t_{n_i}\}$ of $\{t_n\}$ such that

$$\limsup_{n \rightarrow \infty} \langle (\gamma f - A)z, t_n - z \rangle = \lim_{i \rightarrow \infty} \langle (\gamma f - A)z, t_{n_i} - z \rangle. \quad (4.1)$$

Since $\{t_{n_i}\}$ is bounded, there exists a subsequence $\{t_{n_{i_j}}\}$ of $\{t_{n_i}\} \subseteq K$ which converges weakly to some $w \in C$. Without loss of generality, we can assume that $t_{n_i} \rightharpoonup w$. Now, we prove that $w \in \text{Fix}(S)$. Assume that $w \notin \text{Fix}(S)$. Since $t_{n_i} \rightharpoonup w$ and $T(s)w \neq w$, from Opial's conditions (2.3) and Lemma 3.4 (P3), we have

$$\begin{aligned} \liminf_{i \rightarrow \infty} \|t_{n_i} - w\| &< \liminf_{i \rightarrow \infty} \|t_{n_i} - T(s)w\| \\ &\leq \liminf_{i \rightarrow \infty} (\|t_{n_i} - T(s)t_{n_i}\| + \|T(s)t_{n_i} - T(s)w\|) \\ &\leq \liminf_{i \rightarrow \infty} \|t_{n_i} - w\|, \end{aligned}$$

which is a contradiction. Thus, we obtain $w \in \text{Fix}(S)$. Now from (2.1), we have

$$\begin{aligned} \limsup_{n \rightarrow \infty} \langle (\gamma f - A)z, x_n - z \rangle &= \limsup_{n \rightarrow \infty} \langle (\gamma f - A)z, t_n - z \rangle \\ &\leq \limsup_{i \rightarrow \infty} \langle (\gamma f - A)z, t_{n_i} - z \rangle \\ &= \langle (\gamma f - A)z, w - z \rangle \\ &\leq 0. \end{aligned} \quad (4.2)$$

Now we prove that x_n is strongly convergence to z .

$$\begin{aligned} \|x_{n+1} - z\|^2 &= \alpha_n \langle \gamma f(x_n) - Az, x_{n+1} - z \rangle + \langle (1 - \alpha_n A)(t_n - z), x_{n+1} - z \rangle \\ &\leq \alpha_n \langle \gamma f(x_n) - f(z), x_{n+1} - z \rangle + \langle \gamma f(z) - Az, x_{n+1} - z \rangle \\ &\quad + \|1 - \alpha_n A\| \|t_n - z\| \|x_{n+1} - z\| \\ &\leq \alpha_n \alpha \gamma \|x_n - z\| \|x_{n+1} - z\| + \alpha_n \langle \gamma f(z) - Az, x_{n+1} - z \rangle \\ &\quad + (1 - \alpha_n \bar{\gamma}) \left\| \frac{x_n + x_{n+1}}{2} - z \right\| \|x_{n+1} - z\| \\ &\leq \alpha_n \alpha \gamma \|x_n - z\| \|x_{n+1} - z\| + \alpha_n \langle \gamma f(z) - Az, x_{n+1} - z \rangle \\ &\quad + \frac{1 - \alpha_n \bar{\gamma}}{2} (\|x_n - z\| + \|x_{n+1} - z\|) \|x_{n+1} - z\| \\ &= \frac{1 - \alpha_n \bar{\gamma} + 2\alpha_n \alpha \gamma}{2} \|x_n - z\| \|x_{n+1} - z\| + \frac{1 - \alpha_n \bar{\gamma}}{2} \|x_{n+1} - z\|^2 \\ &\quad + \alpha_n \langle \gamma f(z) - Az, x_{n+1} - z \rangle \\ &\leq \frac{1 - \alpha_n (\bar{\gamma} - 2\alpha \gamma)}{4} (\|x_n - z\|^2 + \|x_{n+1} - z\|^2) + \frac{1 - \alpha_n \bar{\gamma}}{2} \|x_{n+1} - z\|^2 \\ &\quad + \alpha_n \langle \gamma f(z) - Az, x_{n+1} - z \rangle \\ &\leq \frac{1 - \alpha_n (\bar{\gamma} - 2\alpha \gamma)}{4} \|x_n - z\|^2 + \frac{3}{4} \|x_{n+1} - z\|^2 + \alpha_n \langle \gamma f(z) - Az, x_{n+1} - z \rangle. \end{aligned}$$

This implies that

$$4\|x_{n+1} - z\|^2 \leq (1 - \alpha_n (\bar{\gamma} - 2\alpha \gamma)) \|x_n - z\|^2 + 3\|x_{n+1} - z\|^2 + 4\alpha_n \langle \gamma f(z) - Az, x_{n+1} - z \rangle.$$

Then

$$\begin{aligned} \|x_{n+1} - z\|^2 &\leq (1 - \alpha_n(\bar{\gamma} - 2\alpha\gamma))\|x_n - z\|^2 + 4\alpha_n\langle\gamma f(z) - Az, x_{n+1} - z\rangle \\ &= (1 - l_n)\|x_n - z\|^2 + 4\alpha_n\langle\gamma f(z) - Az, x_{n+1} - z\rangle, \end{aligned} \quad (4.3)$$

where $l_n = \alpha_n(\bar{\gamma} - 2\alpha\gamma)$.

Since $\lim_{n \rightarrow \infty} \alpha_n = 0$ and $\sum_{n=0}^{\infty} \alpha_n = \infty$, it is easy to see that $\lim_{n \rightarrow \infty} l_n = 0$, $\sum_{n=0}^{\infty} l_n = \infty$. Hence, from (4.2) and (4.3) and Lemma 2.5, we deduce that $x_n \rightarrow z$, where $z = P_{\Theta}(I - A + \gamma f)z$. \square

5. NUMERICAL EXAMPLES

In this section, we give some examples and numerical results for supporting our main theorem. All the numerical results have been produced in Matlab 2017 on a Linux workstation with a 3.8 GHZ Intel annex processor and 8 Gb of memory

Example 5.1. Consider a Fredholm integral equation of the following form

$$x(t) = g(t) + \int_0^t F(t, k, x(k)) dk, \quad t \in [0, 1], \quad (5.1)$$

where g is a continuous function on $[0, 1]$ and $F : [0, 1] \times [0, 1] \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous and satisfies the following condition

$$|F(t, k, x) - F(t, k, y)| \leq |x - y|, \quad \forall t, s \in [0, 1], \quad x, y \in \mathbb{R},$$

then equation (5.1) has at least one solution in $L^2[0, 1]$ (see [9]).

Define a mapping $T(s) : L^2[0, 1] \rightarrow L^2[0, 1]$ by

$$(T(s)x)(t) = e^{-2s}(g(t) + \int_0^t F(t, k, x(k)) dk), \quad t \in [0, 1].$$

It is easy to observe that $S = \{T(s) : s \in [0, +\infty)\}$ is nonexpansive semigroup. In fact, we have, for $x, y \in L^2[0, 1]$,

$$\begin{aligned} \|T(s)x - T(s)y\|^2 &= \int_0^1 |(T(s)x)(t) - (T(s)y)(t)|^2 dt \\ &= \int_0^1 |e^{-2s} \int_0^1 (F(t, k, x(k)) - F(t, k, y(k))) dk|^2 dt \\ &\leq \int_0^1 (\int_0^1 |x(k) - y(k)|^2 dk) dt \\ &= \int_0^1 |x(k) - y(k)|^2 dk \\ &= \|x - y\|^2. \end{aligned}$$

This means that to find the solution of integral equation (5.1) is reduced to find a fixed point of the nonexpansive semigroup S in $L^2[0, 1]$.

For any given function $x_0 \in L^2[0, 1]$, define a sequence of functions x_n in $L^2[0, 1]$ by

$$x_{n+1} = \alpha_n \gamma f(x_n) + (1 - \alpha_n A) \frac{1}{s_n} \int_0^{s_n} T(s) \left(\frac{x_n + x_{n+1}}{2} \right) ds$$

satisfying the conditions of Algorithm 3.1. Then the sequence $\{x_n\}$ converges strongly in $L^2[0, 1]$ to the solution of integral equation (5.1) which is also a solution of the following variational inequality

$$\langle (\gamma f - A)z, y - z \rangle \leq 0, \quad \forall y \in \text{Fix}(S).$$

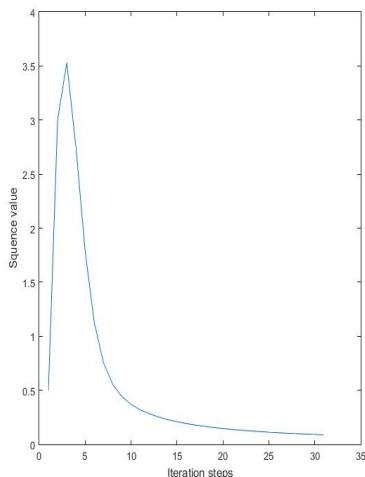
Example 5.2. Let $H = \mathbb{R}$, the set of all real numbers, with the inner product defined by $\langle x, y \rangle = xy$, $\forall x, y \in \mathbb{R}$, and induced usual norm $|\cdot|$. Let $C = [-3, 0]$; Let $f(x) = \frac{1}{5}(x+2)$, $A(x) = \frac{1}{3}x$ and let, for each $x \in C$, $T(s)x = \frac{1}{1+3s}x$. Then there exist unique sequences $\{x_n\} \subset \mathbb{R}$ generated by the iterative scheme

$$x_{n+1} = \frac{6}{5}(x_n + 2) + (1 - \frac{3}{n}A) \frac{1}{s_n} \int_0^{s_n} \frac{1}{1+3s} (\frac{x_n + x_{n+1}}{2}) ds \quad (5.2)$$

where $\alpha_n = \frac{3}{n}$ and $s_n = n$. Then $\{x_n\}$ converges to $\{0\} \in \text{Fix}(S)$. f is contraction mapping with constant $\alpha = \frac{1}{3}$ and A is a strongly positive bounded linear operator with constant $\bar{\gamma} = 1$ on C . Therefore, we can choose $\gamma = 2$ which satisfies $0 < \gamma < \frac{\bar{\gamma}}{\alpha} < \gamma + \frac{1}{\alpha}$. Furthermore, it is easy to observe that $\text{Fix}(S) = \{0\} \neq \emptyset$. After simplification, scheme (5.2) reduce to

$$x_{n+1} = \frac{\frac{12}{5n} + \frac{1}{n}(\frac{6}{5} + \frac{1}{6}(1 - \frac{1}{n}) \ln(1 + 3n))x_n}{1 - \frac{1}{6n}(1 - \frac{1}{n}) \ln(1 + 3n)}.$$

Following the proof of Theorem 4.1, we obtain that $\{x_n\}$ converges strongly to $w = \{0\} \in \text{Fix}(S)$.



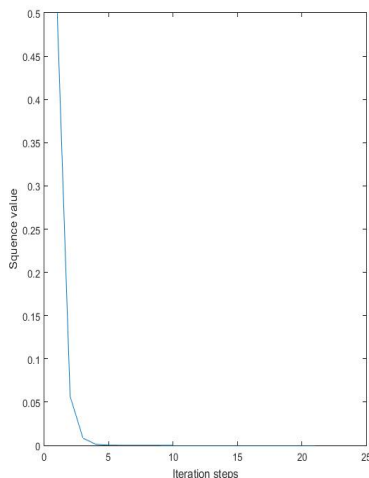
Example 5.3. Let $H = \mathbb{R}$, the set of all real numbers, with the inner product defined by $\langle x, y \rangle = xy$, $\forall x, y \in \mathbb{R}$, and induced usual norm $|\cdot|$. Let $C = [0, 2]$; Let $f(x) = \frac{1}{8}x$, $A(x) = 2x$ and let, for each $x \in C$, $T(s)x = e^{-2s}x$. Then there exist unique sequences $\{x_n\} \subset \mathbb{R}$ generated by the iterative scheme

$$x_{n+1} = \frac{1}{4\sqrt{n}}x_n + (1 - \frac{1}{\sqrt{n}}A) \frac{1}{s_n} \int_0^{s_n} e^{-2s} (\frac{x_n + x_{n+1}}{2}) ds \quad (5.3)$$

where $\alpha_n = \frac{1}{\sqrt{n}}$ and $s_n = 2n$. Then $\{x_n\}$ converges to $\{0\} \in \text{Fix}(S)$. f is contraction mapping with constant $\alpha = \frac{1}{5}$ and A is a strongly positive bounded linear operator with constant $\bar{\gamma} = 1$ on C . Therefore, we can choose $\gamma = 2$ which satisfies $0 < \gamma < \frac{\bar{\gamma}}{\alpha} < \gamma + \frac{1}{\alpha}$. Furthermore, it is easy to observe that $\text{Fix}(S) = \{0\} \neq \emptyset$. After simplification, scheme (5.3) reduce to

$$x_{n+1} = \frac{\frac{1}{4\sqrt{n}} - \frac{1}{8n}(1 - \frac{2}{\sqrt{n}})(e^{-4n} - 1)}{1 + \frac{1}{8n}(1 - \frac{2}{\sqrt{n}})(e^{-4n} - 1)} x_n.$$

Following the proof of Theorem 4.1, we obtain that $\{x_n\}$ converges strongly to $w = \{0\} \in \text{Fix}(S)$.



6. CONCLUSION

We have proposed a viscosity nonlinear midpoint algorithm (VNMA) in real Hilbert spaces. The strong convergence of iteration sequence generated by the algorithm to a solution of VNMA is obtained. Some numerical examples are also provided to illustrate the convergence of proposed algorithm.

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