



COMMON FIXED POINT THEOREMS FOR SOME CONTRACTIVE CONDITION WITH φ -MAPPING IN COMPLEX VALUED B-METRIC SPACES

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ABSTRACT. In this paper, by using the concept of φ -mappings introduced by Mohanta and Maitra [8], we can prove the existence and the uniqueness of common fixed points for some generalized contractive mappings in complex-valued b-metric spaces. Our results extend and improve the results of Tripathi and Dubey [12] and many others.

KEYWORDS: common fixed point, complex-valued metric space, complex valued b-metric space.

AMS Subject Classification: :46C05, 47D03, 47H09, 47H10, 47H20.

1. INTRODUCTION

The concept of a metric space was introduced by Frechet in 1906 [7]. Many mathematicians studied the existence and the uniqueness of fixed points by using the Banach contraction principle. The principle was also proved in some generalized metric spaces, see [5].

Fixed point theorems in metric spaces have been studied extensively by many researchers as in [13, 6] and [11]. In 1989, Bakhtin [3] introduced the notion of b-metric spaces. After that, many researchers extended fixed point theorems from metric spaces to b-metric spaces, for example in [1, 2]

In 2011, A. Azam, B. Fisher and M. Khan [2] introduced the notion of complex valued metric spaces and established sufficient conditions for the existence of common fixed points of a pair of mappings satisfying a contractive condition. A complex valued metric space is a generalization of the classical metric space. Bhatt et al. [4] have proved a common fixed point theorem for weakly compatible mappings in a complex valued metric space. In 2013, Mohanta and Maitra [8], introduced the concept of common fixed points with φ -mapping in complex valued metric spaces, In 2017, Zada et. al. [14], proved common fixed point theorems in complex valued metric spaces with $(E.A)$ and (CLR) properties.

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Article history : Received 3 March 2021; Accepted 29 March 2021.

The aim of this paper is to introduce some contractive conditions of two mappings by using the concept of φ -mappings and prove the existence and the uniqueness of common fixed points in complex valued b-metric spaces. Therefore, our results are comprehensive the results of [8] and [12].

2. PRELIMINARIES

In this section, we present some definitions and lemmas for using in section 3, and define the definition of b-metric space in the complex plane.

Definition 2.1. Let X be a nonempty set. A function $d : X \times X \rightarrow [0, \infty)$ is called a metric if for $x, y, z \in X$ the following conditions are satisfied.

- (i) $d(x, y) = 0$ if and only if $x = y$;
- (ii) $d(x, y) = d(y, x)$;
- (iii) $d(x, z) \leq d(x, y) + d(y, z)$.

The pair (X, d) is called a metric space, and d is called a metric on X .

Next, we suppose the definition of b-metric space, this space is generalized than metric spaces.

Definition 2.2. [3] Let X be a nonempty set and $s \geq 1$ be a given real number. A function $d : X \times X \rightarrow [0, \infty)$ is called a b-metric if for all $x, y, z \in X$ the following conditions are satisfied.

- (i) $d(x, y) = 0$ if and only if $x = y$;
- (ii) $d(x, y) = d(y, x)$;
- (iii) $d(x, z) \leq s[d(x, y) + d(y, z)]$.

The pair (X, d) is called a b-metric space. The number $s \geq 1$ is called the coefficient of (X, d) .

The following is some example for b-metric spaces.

Example 2.3. [3] Let (X, d) be a metric space. The function $\rho(x, y)$ is defined by $\rho(x, y) = (d(x, y))^2$. Then (X, ρ) is a b-metric space with coefficient $s = 2$. This can be seen from the nonnegativity property and triangle inequality of metric to prove the property (iii).

There is a completeness property in real number but on order relation is not well-defined in complex numbers. Before giving the definition of complex valued metric spaces and complex-valued b-metric spaces, we define partial order in complex numbers (see [9]). Let \mathbb{C} be the set of complex numbers and $z_1, z_2 \in \mathbb{C}$. Define partial order relation \preceq on \mathbb{C} as follows;

$$z_1 \preceq z_2 \text{ if and only if } \operatorname{Re}(z_1) \leq \operatorname{Re}(z_2) \text{ and } \operatorname{Im}(z_1) \leq \operatorname{Im}(z_2).$$

This means that we would have $z_1 \preceq z_2$ if and only if one of the following conditions holds:

- (i) $\operatorname{Re}(z_1) = \operatorname{Re}(z_2)$ and $\operatorname{Im}(z_1) = \operatorname{Im}(z_2)$,
- (ii) $\operatorname{Re}(z_1) < \operatorname{Re}(z_2)$ and $\operatorname{Im}(z_1) = \operatorname{Im}(z_2)$,
- (iii) $\operatorname{Re}(z_1) = \operatorname{Re}(z_2)$ and $\operatorname{Im}(z_1) < \operatorname{Im}(z_2)$,
- (iv) $\operatorname{Re}(z_1) < \operatorname{Re}(z_2)$ and $\operatorname{Im}(z_1) < \operatorname{Im}(z_2)$.

If one of the conditions (ii), (iii), and (iv) holds, then we write $z_1 \prec z_2$. From the above partial order relation we have the following remark.

Remark 2.4. We can easily check the following:

- (i) If $a, b \in \mathbb{R}, 0 \leq a \leq b$ and $z_1 \preceq z_2$ then $az_1 \preceq bz_2, \forall z_1, z_2 \in \mathbb{C}$.
- (ii) If $0 \preceq z_1 \prec z_2$ then $|z_1| < |z_2|$.
- (iii) If $z_1 \preceq z_2$ and $z_2 \prec z_3$ then $z_1 \prec z_3$.
- (iv) If $z \in \mathbb{C}$, for $a, b \in \mathbb{R}$ and $a \leq b$, then $az \preceq bz$.

A b-metric on a b-metric sapce is a function having real value. Based on the definition of partial order on complex number, real-valued b-metric can be generalized into complex-valued b-metric as follows.

Definition 2.5. [2] Let X be a nonempty set. A function $d : X \times X \rightarrow \mathbb{C}$ is called a complex valued metric on X if for all $x, y, z \in \mathbb{C}$, the following conditions are satisfied:

- (i) $0 \preccurlyeq d(x, y)$ and $d(x, y) = 0$ if and only if $x = y$,
- (ii) $d(x, y) = d(y, x)$,
- (iii) $d(x, z) \preccurlyeq d(x, y) + d(y, z)$.

Then d is called a complex valued metric on X and (X, d) is called a complex valued metric space.

Next, we give the definition of complex valued b-metric space.

Definition 2.6. [11] Let X be a nonempty set and let $s \geq 1$ be a given real number. A function $d : X \times X \rightarrow \mathbb{C}$ is called a complex valued b-metric on X if, for all $x, y, z \in \mathbb{C}$, the following conditions are satisfied:

- (i) $0 \preccurlyeq d(x, y)$ and $d(x, y) = 0$ if and only if $x = y$,
- (ii) $d(x, y) = d(y, x)$,
- (iii) $d(x, z) \preccurlyeq s[d(x, y) + d(y, z)]$.

The pair (X, d) is called a complex valued b-metric space. We see that if $s = 1$ then (X, d) is complex valued metric space which is defined in Definition 2.5. The following example is some example of complex valued b-metric space.

Example 2.7. [11] Let $X = \mathbb{C}$. Define the mapping $d : \mathbb{C} \times \mathbb{C} \rightarrow \mathbb{C}$ by $d(x, y) = |x - y|^2 + i|x - y|^2$ for all $x, y \in X$. Then (\mathbb{C}, d) is complex valued b-metric space with $s = 2$.

Definition 2.8. [10] Let (X, d) be a complex valued b-metric space.

(i) A point $x \in X$ is called interior point of set $A \subseteq X$ if there exists $0 \prec r \in \mathbb{C}$ such that

$$B(x, r) = \{y \in Y : d(x, y) \prec r\} \subseteq A.$$

(ii) A point $x \in X$ is called limit point of a set A if for every $0 \prec r \in \mathbb{C}$, $B(x, r) \cap (A - x) \neq \emptyset$

(iii) A subset $A \subseteq X$ is open if each element of A is an interior point of A .

(iv) A subset $A \subseteq X$ is closed if each limit point of A is contained in A .

Definition 2.9. [10] Let (X, d) be complex valued b-metric space, $\{x_n\}$ be a sequence in X and $x \in X$.

(i) The sequence $\{x_n\}$ is converges to $x \in X$ if for every $0 \prec r \in \mathbb{C}$ there exists $N \in \mathbb{N}$ such that for all $n \geq N$, $d(x_n, x) \prec r$. Thus x is the limit of (x_n) and we write $\lim_{n \rightarrow \infty} x_n = x$ or $x_n \rightarrow x$ as $n \rightarrow \infty$.

(ii) The sequence $\{x_n\}$ is said to be a Cauchy sequence if for ever $0 \prec r \in \mathbb{C}$ there exists $N \in \mathbb{N}$ such that for all $n \geq N$, $d(x_n, x_{n+m}) \prec r$, where $m \in \mathbb{N}$.

(iii) If for every Cauchy sequence in X is convergent, then (X, d) is said to be a complete complex valued b-metric space.

Definition 2.10. [8] Let $P = \{z \in \mathbb{C} : \operatorname{Re}(z) \geq 0 \text{ and } \operatorname{Im}(z) \geq 0\}$. A nondecreasing mapping $\varphi : P \rightarrow P$ is called a φ -mapping if

- (i) $\varphi(0) = 0$ and $0 \prec \varphi(z) \prec z$ for $z \in P - \{0\}$;
- (ii) $\varphi(z) \prec z$ for every $z \succ 0$;
- (iii) $\lim_{n \rightarrow \infty} \varphi^n(z) = 0$ for every $z \in P - \{0\}$.

Lemma 2.11. [10] Let (X, d) be a complex valued b-metric space and let $\{x_n\}$ be a sequence in X . Then $\{x_n\}$ converges to x if and only if $|d(x_n, x)| \rightarrow 0$ as $n \rightarrow \infty$.

Lemma 2.12. [10] Let (X, d) be a complex valued b-metric space and let $\{x_n\}$ be a sequence in X . Then $\{x_n\}$ is a Cauchy sequence if and only if $|d(x_n, x_{n+m})| \rightarrow 0$ as $n \rightarrow \infty$, where $m \in \mathbb{N}$.

3. MAIN RESULTS

In this section, we define some contraction by using a φ -mapping, and prove the existence and uniqueness of common fixed point theorem in a complete complex valued b-metric space.

Theorem 3.1. *Let (X, d) be a complete complex valued b-metric space and the mappings $S, T : X \rightarrow X$ are self mappings satisfying the condition*

$$d(Sx, Ty) \preceq \varphi[\lambda \frac{d(x, Sx)d(x, Ty) + d(y, Ty)d(y, Sx)}{d(x, Ty) + d(y, Sx)} + \mu d(x, y)] \quad (3.1)$$

for all $x, y \in X$, where $d(x, Ty) + d(y, Sx) \neq 0$ and λ, μ are nonnegative reals with the condition $\lambda + \mu < 1$. If φ is continuous then S and T has a unique common fixed point.

Proof. Let $x_0 \in X$ be an arbitrary point. We define

$$\begin{aligned} x_{2n+1} &= Sx_{2n} \text{ and} \\ x_{2n+2} &= Tx_{2n+1}, n = 0, 1, 2, 3, \dots \end{aligned}$$

By equations (3.1) and (3.2), we consider

$$\begin{aligned} d(x_{2n+1}, x_{2n+2}) &= d(Sx_{2n}, Tx_{2n+1}) \\ &\preceq \varphi[\lambda \frac{d(x_{2n}, Sx_{2n})d(x_{2n}, Tx_{2n+1}) + d(x_{2n+1}, Tx_{2n+1})d(x_{2n+1}, Sx_{2n})}{d(x_{2n}, Tx_{2n+1}) + d(x_{2n+1}, Sx_{2n})} \\ &\quad + \mu d(x_{2n}, x_{2n+1})] \\ &\preceq \varphi[\lambda \frac{d(x_{2n}, x_{2n+1})d(x_{2n}, x_{2n+2}) + d(x_{2n+1}, x_{2n+2})d(x_{2n+1}, x_{2n+1})}{d(x_{2n}, x_{2n+2}) + d(x_{2n+1}, x_{2n+1})} \\ &\quad + \mu d(x_{2n}, x_{2n+1})]. \end{aligned} \quad (3.2)$$

From $\lambda + \mu < 1$ and (3.2), we have

$$\begin{aligned} d(x_{2n+1}, x_{2n+2}) &= \varphi[\lambda \frac{d(x_{2n}, x_{2n+1})d(x_{2n}, x_{2n+2})}{d(x_{2n}, x_{2n+2})} + \mu d(x_{2n}, x_{2n+1})] \\ &\preceq \varphi[\lambda d(x_{2n}, x_{2n+1}) + \mu d(x_{2n}, x_{2n+1})] \\ &= \varphi[(\lambda + \mu)d(x_{2n}, x_{2n+1})] \\ &\preceq \varphi[d(x_{2n}, x_{2n+1})]. \end{aligned}$$

Similarly, we have

$$\begin{aligned} d(x_{2n}, x_{2n+1}) &= \varphi[\lambda \frac{d(x_{2n-1}, x_{2n})d(x_{2n-1}, x_{2n+1})}{d(x_{2n-1}, x_{2n+1})} + \mu d(x_{2n-1}, x_{2n})] \\ &\preceq \varphi[\lambda d(x_{2n-1}, x_{2n}) + \mu d(x_{2n-1}, x_{2n})] \\ &= \varphi[(\lambda + \mu)d(x_{2n-1}, x_{2n})] \\ &\preceq \varphi[d(x_{2n-1}, x_{2n})]. \end{aligned}$$

By mathematical induction, implies that

$$\begin{aligned} d(x_{2n+1}, x_{2n+2}) &\preceq \varphi(\varphi(\varphi(\dots \varphi(d(x_0, x_1)))))) \\ &= \varphi^{2n+1}d(x_0, x_1). \end{aligned} \quad (3.3)$$

From (3.3) and Definition 2.10, we conclude that

$$d(x_{n+1}, x_{n+2}) \preceq \varphi^{n+1}d(x_0, x_1) \quad (3.4)$$

So, for $m > n$ and Definition 2.6, we consider

$$\begin{aligned} d(x_n, x_{n+m}) &\preceq s[d(x_n, x_{n+1}) + d(x_{n+1}, x_{n+m})] \\ &\preceq sd(x_n, x_{n+1}) + sd(x_{n+1}, x_{n+m}) \\ &\preceq sd(x_n, x_{n+1}) + s[s(d(x_{n+1}, x_{n+2}) + d(x_{n+2}, x_{n+m}))] \\ &\preceq sd(x_n, x_{n+1}) + s^2(d(x_{n+1}, x_{n+2}) + s^2d(x_{n+2}, x_{n+m})) \\ &\preceq sd(x_n, x_{n+1}) + s^2(d(x_{n+1}, x_{n+2}) + s^2d(x_{n+2}, x_{n+m})) \end{aligned}$$

$$\begin{aligned}
& +s^{n+m-1}d(x_{n+m-2}, x_{n+m-1}) + \dots + s^m d(x_{n+m-1}, x_{n+m}) \\
& \preccurlyeq sd(x_n, x_{n+1}) + s^2(d(x_{n+1}, x_{n+2}) + s^3d(x_{n+2}, x_{n+3}) + s^3d(x_{n+3}, x_{n+m}) \\
& \quad + \dots + s^{n+m-1}d(x_{n+m-2}, x_{n+m-1}) + s^m d(x_{n+m-1}, x_{n+m}) \\
& \preccurlyeq s\varphi^n d(x_0, x_1) + s^2\varphi^{n+1}(d(x_0, x_1) + s^3d(x_0, x_1) + s^3\varphi^{n+2}d(x_0, x_1) \\
& \quad + \dots + s^{n+m-1}\varphi^{n+m-2}d(x_0, x_1)s^m\varphi^{n+m-1}d(x_0, x_1) \\
& = [s\varphi^n + s^2\varphi^{n+1} + s^3 + s^3\varphi^{n+2} + s^{n+m-1}\varphi^{n+m-2} + s^m\varphi^{n+m-1}]d(x_0, x_1).
\end{aligned} \tag{3.5}$$

From remark 2.4 (ii), we have

$$|d(x_n, x_{n+m})| \leq [s\varphi^n + s^2\varphi^{n+1} + s^3 + s^3\varphi^{n+2} + \dots + s^{n+m-1}\varphi^{n+m-2} + s^m\varphi^{n+m-1}]|d(x_0, x_1)|. \tag{3.6}$$

From (3.4), (3.6) and Taking $n \rightarrow \infty$, it follows that $|d(x_n, x_{n+m})| \rightarrow \infty$.

By Lemma 2.12, implies that $\{x_n\}$ is a cauchy sequence in X . Since X is complete, there exists $u \in X$ such that $x_n \rightarrow u$. Now, we show that u is a fixed point of T and S . Consider,

$$\begin{aligned}
d(Su, x_{2n+2}) &= d(Su, Tx_{2n+1}) \\
&\preccurlyeq \varphi(\lambda \frac{d(u, Su)d(u, Tx_{2n+1}) + d(x_{2n+1}, Tx_{2n+1})d(x_{2n+1}, Su)}{d(u, Tx_{2n+1}) + d(x_{2n+1}, Su)} + \mu d(u, x_{2n+1})) \\
&\preccurlyeq \varphi(\lambda \frac{d(u, Su)d(u, x_{2n+2}) + d(x_{2n+1}, x_{2n+2})d(x_{2n+1}, Su)}{d(u, x_{2n+2}) + d(x_{2n+1}, Su)} + \mu d(u, x_{2n+1})).
\end{aligned} \tag{3.7}$$

From φ is a continuous, (3.7), $x_n \rightarrow u$ as $n \rightarrow \infty$ and Definition 2.6 (1), we have

$$\begin{aligned}
d(Su, u) &= \lim_{n \rightarrow \infty} d(Su, x_{2n+1}) \\
&\preccurlyeq \lim_{n \rightarrow \infty} \varphi(\lambda \frac{d(u, Su)d(u, x_{2n+2}) + d(x_{2n+1}, x_{2n+2})d(x_{2n+1}, Su)}{d(u, x_{2n+2}) + d(x_{2n+1}, Su)} + \mu d(u, x_{2n+1})) \\
&= \varphi(\lim_{n \rightarrow \infty} (\lambda \frac{d(u, Su)d(u, x_{2n+2}) + d(x_{2n+1}, x_{2n+2})d(x_{2n+1}, Su)}{d(u, x_{2n+2}) + d(x_{2n+1}, Su)} + \mu d(u, x_{2n+1}))) \\
&= \varphi(\lambda \frac{d(u, Su)d(u, u) + d(u, u)d(u, Su)}{d(u, u) + d(u, Su)} + \mu d(u, u)) \\
&= \varphi(0) = 0.
\end{aligned} \tag{3.8}$$

Thus $u = Su$. Hence u is a fixed point of S . Next, we show that u is a fixed point of T . Consider,

$$\begin{aligned}
d(x_{2n+1}, Tu) &= d(Sx_{2n}, Tu) \\
&\preccurlyeq \varphi(\lambda \frac{d(x_{2n}, Sx_{2n})d(x_{2n}, Tu) + d(u, Tu)d(u, Sx_{2n})}{d(x_{2n}, Tu) + d(u, Sx_{2n})} + \mu d(x_{2n}, u)) \\
&= \varphi(\lambda \frac{d(x_{2n}, x_{2n+1})d(x_{2n}, Tu) + d(u, Tu)d(u, x_{2n+1})}{d(x_{2n}, Tu) + d(u, x_{2n+1})} + \mu d(x_{2n}, u)).
\end{aligned} \tag{3.9}$$

From φ is a continuous, (3.9), $x_n \rightarrow u$ as $n \rightarrow \infty$ and Definition 2.6 (1), we have

$$\begin{aligned}
d(u, Tu) &= \lim_{n \rightarrow \infty} d(x_{2n+1}, Tu) \\
&\preccurlyeq \lim_{n \rightarrow \infty} \varphi(\lambda \frac{d(x_{2n}, x_{2n+1})d(x_{2n}, Tu) + d(u, Tu)d(u, x_{2n+1})}{d(x_{2n}, Tu) + d(u, x_{2n+1})} + \mu d(x_{2n}, u)) \\
&= \varphi(\lim_{n \rightarrow \infty} (\lambda \frac{d(x_{2n}, x_{2n+1})d(x_{2n}, Tu) + d(u, Tu)d(u, x_{2n+1})}{d(x_{2n}, Tu) + d(u, x_{2n+1})} + \mu d(x_{2n}, u))) \\
&= \varphi(\lambda \frac{d(u, u)d(u, Tu) + d(u, Tu)d(u, u)}{d(u, Tu) + d(u, u)} + \mu d(u, u)) \\
&= \varphi(0) = 0.
\end{aligned} \tag{3.10}$$

Thus $u = Tu$. Hence u is a fixed point of T . Therefore, u is a common fixed point of S and T . Finally, we prove the uniqueness of common fixed point of S and T . Suppose that v is a common fixed point of S and T . So $Sv = v = Tv$. Now, we show that $u = v$. Assume that $u \neq v$, we consider

$$\begin{aligned} d(u, v) &= d(Su, Tv) \\ &\preceq \varphi\left(\lambda \frac{d(u, Su)d(u, Tv) + d(v, Tv)d(v, Su)}{d(u, Tv) + d(v, Su)} + \mu d(u, v)\right) \\ &= \varphi\left(\lambda \frac{d(u, u)d(u, v) + d(v, v)d(v, u)}{d(u, v) + d(v, u)} + \mu d(u, v)\right) \\ &= \varphi(\mu d(u, v)). \end{aligned} \quad (3.11)$$

Since $\mu < 1$, we have $\mu d(u, v) < d(u, v)$. By Definition 2.10 (2) and φ is a nondecreasing, we have

$$d(u, v) \preceq \varphi(\mu d(u, v)) \preceq \varphi(d(u, v)) \prec d(u, v). \quad (3.12)$$

From remark 2.4 (ii), taking absolute value of both side, we have

$$|d(u, v)| < |d(u, v)|.$$

It is a contradiction. We can conclude that $u = v$. Therefore u is a uniqueness common fixed point of S and T . \square

From Theorem 3.1, we have the parallel result with the result of Dubey et. al [12] as following.

Corollary 3.2. *Let (X, d) be a complete complex valued b -metric space and the mappings $S, T : X \rightarrow X$ satisfy the condition*

$$d(Sx, Ty) \preceq \lambda \frac{d(x, Sx)d(x, Ty) + d(y, Ty)d(y, Sx)}{d(x, Ty) + d(y, Sx)} + \mu d(x, y) \quad (3.13)$$

for all $x, y \in X$, where $d(x, Ty) + d(y, Sx) \neq 0$ and λ, μ are nonnegative reals with $\lambda + \mu < 1$. If either S or T is continuous and the pair (S, T) is compatible, then S and T has a unique common fixed point.

Proof. If $\varphi = I$ is an identity mapping, then (3.1) reduces to (3.13) and suppose one of S and T is continuous and the pair (S, T) is compatible, then S and T has a unique common fixed point. This completes the proof. \square

Theorem 3.3. *Let (X, d) be a complete complex valued b -metric space and the mappings $S, T : X \rightarrow X$ are self mappings satisfying the condition*

$$d(S^n x, T^n y) \preceq \varphi\left[\lambda \frac{d(x, S^n x)d(x, T^n y) + d(y, T^n y)d(y, S^n x)}{d(x, T^n y) + d(y, S^n x)} + \mu d(x, y)\right] \quad (3.14)$$

for all $x, y \in X$, $n \geq 1$, where $d(x, Ty) + d(y, Sx) \neq 0$ and λ, μ are nonnegative reals with the condition $\lambda + \mu < 1$. If φ is continuous then S and T has a unique common fixed point.

Proof. Suppose $A = S^n$ and $B = T^n$, by Theorem 3.1, there exists a common fixed point u of A and B , such that

$$Au = u = Bu.$$

Thus $S^n u = u$ and $T^n u = u$. We claim that $Su = u$. Assume that $Su \neq u$, we have

$$\begin{aligned} d(Su, u) &= d(S(S^n u), T^n u) \\ &= d(S^n(Su), T^n u) \\ &\preceq \varphi\left[\lambda \frac{d(Su, S^n(Su))d(Su, T^n u) + d(u, T^n u)d(u, S^n(Su))}{d(Su, T^n u) + d(u, S^n(Su))} + \mu d(Su, u)\right] \\ &= \varphi\left[\lambda \frac{d(Su, S(S^n u))d(Su, T^n u) + d(u, T^n u)d(u, S(S^n u))}{d(Su, T^n u) + d(u, S(S^n u))} + \mu d(Su, u)\right] \\ &= \varphi\left[\lambda \frac{d(Su, Su)d(Su, u) + d(u, u)d(u, Su)}{d(Su, u) + d(u, Su)} + \mu d(Su, u)\right] \end{aligned}$$

$$= \varphi [\mu d(Su, u)].$$

From Definition 2.10, we have $d(Su, u) \prec \mu d(Su, u)$. A contradiction, because $\mu < 1$. Hence, $Su = u$. Next, we claim that $Tu = u$. Assume that $Tu \neq u$, we have

$$\begin{aligned} d(u, Tu) &= d(S^n u, T(T^n u)) \\ &= d(S^n u, T^n(Tu)) \\ &\preceq \varphi \left[\lambda \frac{d(u, S^n u)d(u, T^n(Tu)) + d(Tu, T^n(Tu))d(Tu, S^n u)}{d(u, T^n(Tu)) + d(Tu, S^n u)} + \mu d(u, Tu) \right] \\ &= \varphi \left[\lambda \frac{d(u, S^n u)d(u, T(T^n u)) + d(Tu, T(T^n u))d(Tu, S^n u)}{d(u, T(T^n u)) + d(Tu, S^n u)} + \mu d(u, Tu) \right] \\ &= \varphi \left[\lambda \frac{d(u, u)d(u, Tu) + d(Tu, Tu)d(Tu, u)}{d(u, Tu) + d(Tu, u)} + \mu d(u, Tu) \right] \\ &= \varphi [\mu d(u, Tu)]. \end{aligned}$$

From Definition 2.10, we have $d(u, Tu) \prec \mu d(u, Tu)$. A contradiction, because $\mu < 1$. Hence, $Tu = u$. Hence u is a common fixed point of S and T .

Finally, we show that u is a unique fixed point of S and T . Let v be a common fixed point of S and T , thus $S^n v = v = T^n v$. We must show that $u = v$. Assume that $u \neq v$, we have

$$\begin{aligned} d(u, v) &= d(S^n u, T^n v) \\ &\preceq \varphi \left[\lambda \frac{d(u, S^n u)d(u, T^n v) + d(v, T^n v)d(v, S^n u)}{d(u, T^n v) + d(v, S^n u)} + \mu d(u, v) \right] \\ &= \varphi \left[\lambda \frac{d(u, u)d(u, v) + d(v, v)d(v, u)}{d(u, v) + d(v, u)} + \mu d(u, v) \right] \\ &= \varphi [\mu d(u, v)]. \end{aligned}$$

From Definition 2.10, we have $d(u, v) \prec \mu d(u, v)$. A contradiction, because $\mu < 1$. Hence, $u = v$. Therefore, u is a unique common fixed point of S and T . \square

Example 3.4. Let $X = \mathbb{C}$. Define a function $d : X \times X \rightarrow \mathbb{C}$ such that

$$d(z_1, z_2) = |x_1 - x_2|^2 + i|y_1 - y_2|^2,$$

where $z_1 = x_1 + iy_1, z_2 = x_2 + iy_2$.

From Example 18 in [9], it implied that (X, d) is a complete complex valued b -metric space with $s = 2$. Now, we define two self-mappings $S, T : X \rightarrow X$ as follows:

$$Sz = \begin{cases} 0 & \text{if } a, b \in \mathbb{Q}, \\ 2 & \text{if } a \in \mathbb{Q}^C, b \in \mathbb{Q} \\ 2i & \text{if } a, b \in \mathbb{Q}^C \\ 2 + 2i & \text{if } a \in \mathbb{Q}, b \in \mathbb{Q}^C \end{cases} \quad \text{and} \quad Tz = \begin{cases} 0 & \text{if } a, b \in \mathbb{Q}, \\ 1 & \text{if } a \in \mathbb{Q}^C, b \in \mathbb{Q} \\ i & \text{if } a, b \in \mathbb{Q}^C \\ 1 + i & \text{if } a \in \mathbb{Q}, b \in \mathbb{Q}^C \end{cases}$$

where $z = a + bi \in X$. We see that $S^n z = 0 = T^n z$ for $n > 1$, so

$$d(S^n x, T^n y) = 0 \preceq \lambda \frac{d^2(x, y)}{1 + d(x, y)} + \mu d(y, T^n y) + \rho d(x, S^n x),$$

for all $x, y \in X$ and $\lambda, \mu, \rho \geq 0$ with $2(\lambda + \rho) + \mu < 1$. So all conditions of Theorem 3.3 are satisfied to get a unique common fixed point 0 of S and T .

4. ACKNOWLEDGEMENTS

The authors would like to thank Department of Mathematics, faculty of Science and Technology. Moreover, we would like to thank Uttaradit Rajabhat University for financial support.

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