

SET-VALUED PREŠIĆ-REICH TYPE CONTRACTIONS IN CONE METRIC SPACES AND FIXED POINT THEOREMS

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ABSTRACT. The purpose of this paper is to prove some fixed point theorems for set-valued mappings satisfying Prešić-Reich type contractive condition in cone metric spaces, without assuming the normality of cone. Our results generalize some known results in metric and cone metric spaces.

KEYWORDS : Prešić-Reich type; Point-set-cone metric; Cone metric space; Fixed point.

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1. INTRODUCTION

Let (X, d) be a metric space and f be a self-map on X . The mapping f is called a Banach contraction if, there exists $\lambda \in [0, 1)$ such that

$$d(fx, fy) \leq \lambda d(x, y) \text{ for all } x, y \in X. \quad (1.1)$$

The Banach contraction principle states that every Banach contraction on a complete metric space has a fixed point, i.e., there exists a point $x^* \in X$ such that $fx^* = x^*$.

Let X be a nonempty set, 2^X the collection of all possible subsets of X and $f: X \rightarrow 2^X$ be a mapping. Then, f is called a set-valued mapping. Let $x \in X$ be such that $fx \neq \emptyset$, then x is called a fixed point of f if $x \in fx$.

Let A be any nonempty subset of a metric space (X, d) . For $x \in X$, define

$$d(x, A) = \inf\{d(x, y) : y \in A\}.$$

Let $CB(X)$ denotes the set of all nonempty closed bounded subset of X . For $A, B \in CB(X)$, define

$$\begin{aligned} \delta(A, B) &= \sup\{d(x, B) : x \in A\}, \\ H(A, B) &= \max\{\delta(A, B), \delta(B, A)\}. \end{aligned}$$

Then H is a metric on $CB(X)$ and called Pompeiu-Hausdorff (or Hausdorff) metric. A mapping $f: X \rightarrow CB(X)$ is called a Nadler contraction (or a set-valued Banach contraction), if there exists $\lambda \in [0, 1)$ such that

$$H(fx, fy) \leq \lambda d(x, y) \text{ for all } x, y \in X. \quad (1.2)$$

In 1969, Nadler [10] generalized the famous Banach contraction principle for the set-valued mappings defined from a complete metric space X into the set $CB(X)$. Nadler [10] proved the following theorem:

Theorem 1.1. *Let (X, d) be a complete metric space and let f be a set-valued Banach contraction. Then there exists a point $x^* \in X$ such that $x^* \in fx^*$, i.e., f has a fixed point in X .*

On the other hand, for mappings $f: X \rightarrow X$ Kannan [6] introduced the contractive condition:

$$d(fx, fy) \leq \lambda[d(x, fx) + d(y, fy)] \quad (1.3)$$

for all $x, y \in X$, where $\lambda \in [0, 1/2)$ is a constant, and proved a fixed point theorem using (1.3) instead of contractive condition (1.1). The conditions (1.3) and (1.1) are independent, as it was shown by two examples in [7].

Reich [14], generalized the fixed point theorems of Banach and Kannan, using contractive condition: for all $x, y \in X$,

$$d(fx, fy) \leq \alpha d(x, y) + \beta d(x, fx) + \gamma d(y, fy) \quad (1.4)$$

where α, β, γ are nonnegative reals with $\alpha + \beta + \gamma < 1$. An example in [14] shows that the Reich's contractive condition is a proper generalization of contractive conditions of Banach and Kannan.

In 1965, Prešić [12, 13] generalized the Banach contraction principle in product spaces and proved the following theorem.

Theorem 1.2. *Let (X, d) be a complete metric space, k a positive integer and $f: X^k \rightarrow X$ be a mapping satisfying the following contractive type condition:*

$$d(f(x_1, x_2, \dots, x_k), f(x_2, x_3, \dots, x_{k+1})) \leq \sum_{i=1}^k q_i d(x_i, x_{i+1}), \quad (1.5)$$

for every $x_1, x_2, \dots, x_k, x_{k+1} \in X$, where q_1, q_2, \dots, q_k are nonnegative constants such that $q_1 + q_2 + \dots + q_k < 1$. Then there exists a unique point $x \in X$ such that $f(x, x, \dots, x) = x$. Moreover, if x_1, x_2, \dots, x_k are arbitrary points in X and for $n \in \mathbb{N}$, $x_{n+k} = f(x_n, x_{n+1}, \dots, x_{n+k-1})$, then the sequence $\{x_n\}$ is convergent and $\lim x_n = f(\lim x_n, \lim x_n, \dots, \lim x_n)$.

A mapping $f: X^k \rightarrow X$ is called a Prešić type contraction if it satisfies (1.5). The mapping f is called a Prešić-Kannan type contraction if,

$$d(f(x_0, \dots, x_{k-1}), f(x_1, \dots, x_k)) \leq a \sum_{i=0}^k d(x_i, f(x_i, \dots, x_i)), \quad (1.6)$$

for all $x_0, x_1, \dots, x_k \in X$, where the real constant a is such that $0 \leq ak(k+1) < 1$.

In a similar manner to that used by S.B. Prešić [12, 13], when extending Banach contractions to product spaces, Păcurar [11] generalized the Kannan's theorem in product spaces and proved a fixed point theorem for Prešić-Kannan type contractions.

f is called a Prešić-Reich type contraction if,

$$\begin{aligned} d(f(x_0, \dots, x_{k-1}), f(x_1, \dots, x_k)) &\leq \sum_{i=1}^k \alpha_i d(x_{i-1}, x_i) \\ &+ \sum_{i=0}^k \beta_i d(x_i, f(x_i, \dots, x_i)), \end{aligned} \quad (1.7)$$

for all $x_0, x_1, \dots, x_k \in X$, where α_i, β_i are nonnegative constants such that

$$\sum_{i=1}^k \alpha_i + k \sum_{i=0}^k \beta_i < 1.$$

Note that, for $k = 1$ the above definition reduces into the definition due to Reich [14]. Also, Prešić-Banach type contraction (i.e., a mapping f satisfying (1.5)) and Prešić-Kannan type contraction are particular cases of Prešić-Reich type contractions. Malhotra et al. [9] first introduced the notion of Prešić-Reich type contractions (for single-valued case) in cone metric spaces and proved some common fixed point and fixed point results for such mappings.

In 2011, Wardowski [16] introduced the set-valued mappings in cone metric spaces and proved the cone metric version of the result of Nadler [10] (see also [1, 8, 15]). In this paper, we introduced the notion of set-valued Prešić-Reich type contractions in cone metric spaces and prove some fixed point results for such mappings, using the definitions due to Wardowski [16]. Our results generalize and extend the results of Nadler [10], Kannan [6], Reich [14], Prešić [12], Malhotra et al. [9] and Wardowski [16] in the setting of cone metric spaces for set-valued mappings. An example is provided which illustrate the main theorem of this paper.

2. PRELIMINARIES

We use the following definitions and results, consistent with [2] and [3].

Definition 2.1. [3] Let E be a real Banach space and P be a subset of E . The set P is called a cone if

- (i) P is closed, nonempty and $P \neq \{\theta\}$, here θ is the zero vector of E ;
- (ii) $a, b \in \mathbb{R}$, $a, b \geq 0$, $x, y \in P \implies ax + by \in P$;
- (iii) $x \in P$ and $-x \in P \implies x = \theta$.

Given a cone $P \subset E$, we define a partial ordering “ \preceq ” with respect to P by $x \preceq y$ if and only if $y - x \in P$. We write $x \prec y$ to indicate that $x \preceq y$ but $x \neq y$. While $x \ll y$ if and only if $y - x \in P^\circ$, where P° denotes the interior of P . Let P be a cone in a real Banach space E , then P is called normal, if there exist a constant $K > 0$ such that for all $x, y \in E$,

$$\theta \preceq x \preceq y \text{ implies } \|x\| \leq K\|y\|.$$

The least positive number K satisfying the above inequality is called the normal constant of P . A cone P is called solid if $P^\circ \neq \emptyset$.

Definition 2.2. [3] Let X be a nonempty set, E be a real Banach space with cone P . Suppose that the mapping $d : X \times X \rightarrow E$ satisfies:

- 1. $\theta \preceq d(x, y)$, for all $x, y \in X$ and $d(x, y) = \theta$ if and only if $x = y$;
- 2. $d(x, y) = d(y, x)$ for all $x, y \in X$;
- 3. $d(x, y) \preceq d(x, z) + d(y, z)$, for all $x, y, z \in X$.

Then d is called a *cone metric* on X , and (X, d) is called a cone metric space. If the underlying cone is normal, then (X, d) is called a normal cone metric space.

The following lemma will be useful in the sequel.

Lemma 2.3. [4, 5] *Let E be a real Banach space, P a solid cone in E . Then:*

- (i) *If $\{a_n\}$ is a sequence in P , $a_n \rightarrow \theta$ then, for every $c \in P^\circ$ there exists $n \in \mathbb{N}$ such that, $a_n \ll c$ for all $n > n_0$.*
- (ii) *If $u, v, w \in P$ and $u \preceq v$, $v \ll w$ then $u \ll w$.*
- (iii) *If $u, v, w \in P$ and $u \ll v$, $v \preceq w$ then $u \ll w$.*
- (iv) *If $u \in P$ and $u \ll c$ for each $c \in P^\circ$, then $u = \theta$.*

Let (X, d) be a cone metric space with cone P . A subset $A \subset X$ is called closed if for any sequence $\{x_n\} \subset A$ convergent to x , we have $x \in A$.

Denote by $N(X)$ a collection of all nonempty subsets of X and by $C(X)$ a collection of all nonempty closed subsets of X .

The following definitions can be found in [16].

Definition 2.4. [16] Let (X, d) be a cone metric space and let \mathcal{A} be a collection of nonempty subsets of X . A map $H: \mathcal{A} \times \mathcal{A} \rightarrow E$ is called a H -cone metric with respect to d if for any $A_1, A_2 \in \mathcal{A}$ the following conditions hold:

- (H1) $H(A_1, A_2) = \theta \implies A_1 = A_2$;
- (H2) $H(A_1, A_2) = H(A_2, A_1)$;
- (H3) $\forall_{c \in E, \theta \ll c} \forall_{x \in A_1} \exists_{y \in A_2} d(x, y) \preceq H(A_1, A_2) + c$;
- (H4) One of the following is satisfied:
 - (i) $\forall_{c \in E, \theta \ll c} \exists_{x \in A_1} \forall_{y \in A_2} H(A_1, A_2) \preceq d(x, y) + c$;
 - (ii) $\forall_{c \in E, \theta \ll c} \exists_{x \in A_2} \forall_{y \in A_1} H(A_1, A_2) \preceq d(x, y) + c$.

The following are some examples of H -cone metrics.

Example 2.5. [16] Let (X, d) be a cone metric space and let $\mathcal{A} = \{\{x\} : x \in X\}$. Define the mapping $H: \mathcal{A} \times \mathcal{A} \rightarrow E$ by the formula

$$H(\{x\}, \{y\}) = d(x, y) \text{ for all } x, y \in X,$$

is a H -cone metric with respect to d .

Example 2.6. [16] Let (X, d) be a metric space and let \mathcal{A} be the family of all nonempty, closed bounded subsets of X . Then the mapping $H: \mathcal{A} \times \mathcal{A} \rightarrow \mathbb{R}^+$ given by the formula

$$H(A, B) = \max \left\{ \sup_{x \in A} d(x, B), \sup_{y \in B} d(y, A), A, B \in \mathcal{A} \right\}$$

which is called a Hausdorff metric, is a H -cone metric with respect to d .

The following lemma shows that a H -cone metric with respect to the cone metric d , is itself a cone metric when $\mathcal{A} \subset N(X)$.

Lemma 2.7. [16] *Let (X, d) be a cone metric space and let $\mathcal{A} \subset N(X)$, $\mathcal{A} \neq \emptyset$. If $H: \mathcal{A} \times \mathcal{A} \rightarrow E$ is a H -cone metric with respect to d then a pair (\mathcal{A}, H) is a cone metric space.*

Wardowski [16] proved the following cone metric version of result of Nadler [10].

Theorem 2.1. [16] *Let (X, d) be a complete cone metric space with a normal cone P with a normal constant K , \mathcal{A} be a nonempty collection of nonempty closed subsets*

of X and let $H: \mathcal{A} \times \mathcal{A} \longrightarrow E$ be a H -cone metric with respect to d . If for a map $f: X \longrightarrow \mathcal{A}$ there exists $\lambda \in (0, 1)$ such that

$$H(fx, fy) \preceq \lambda d(x, y) \text{ for all } x, y \in X, \quad (2.1)$$

then the set of all fixed points of f is nonempty.

3. MAIN RESULTS

In this section, we introduce various types of set-valued Prešić type contractions, the point-set-cone metric and prove some fixed point results for set-valued Prešić type contractions in cone metric spaces. In further discussion, we assume that the cones under consideration are solid cones, i.e., $P^\circ \neq \emptyset$.

First, we define the point-set-cone metric between a point and a subset of cone metric spaces which is an extension and generalization of the distance of point from a set in ordinary metric spaces.

Definition 3.1. Let (X, d) be a cone metric space and let \mathcal{A} be a nonempty collection of nonempty subsets of X . A map $d_s: X \times \mathcal{A} \longrightarrow E$ is called the point-set-cone metric with respect to d if for all $x \in X$, $A \in \mathcal{A}$ the following conditions hold:

- (PS1) $\theta \preceq d_s(x, A)$ and $d_s(x, A) = \theta \implies x \in A$;
- (PS2) $\forall a \in A \ d_s(x, A) \preceq d(x, a)$.

Let us observe that for each cone metric d the family of point-set-cone metrics with respect to d is nonempty and each point-set-cone metric depends on the shape of the family \mathcal{A} . See the following examples:

Example 3.2. Let (X, d) be a cone metric space and let

$$\mathcal{A} = \{\{x\} : x \in X\}.$$

Then, the mapping $d_s: X \times \mathcal{A} \longrightarrow E$ defined by the formula

$$d_s(x, \{y\}) = d(x, y) \text{ for all } x, y \in X,$$

is a point-set-cone metric with respect to d .

Example 3.3. Let (X, d) be a metric space and let \mathcal{A} be the family of all nonempty, closed and bounded subsets of X . Then the mapping $d_s: X \times \mathcal{A} \longrightarrow \mathbb{R}^+$ given by the formula

$$d_s(x, A) = \inf\{d(x, a) : a \in A\}$$

which is called the distance of point x from the set A , is a point-set-cone metric with respect to d .

Example 3.4. Let $E = \mathbb{R}^2$, the Euclidean plane, $P = \{(x, y) \in \mathbb{R}^2 : x, y \geq 0\}$ be the cone in E and $X = \{(x, 0) \in \mathbb{R}^2 : 0 \leq x \leq 1\} \cup \{(0, x) \in \mathbb{R}^2 : 0 \leq x \leq 1\}$. Let $X = \{(x, 0), (0, x) : 0 \leq x \leq 1\}$ and the mapping $d: X \times X \longrightarrow E$ by defined by

$$d((x, 0), (y, 0)) = |x - y| (0, 1), d((0, x), (0, y)) = |x - y| (1, 0),$$

$$d((x, 0), (0, y)) = d((0, y), (x, 0)) = (y, x).$$

Then (X, d) is a cone metric space. Let $\mathcal{A} = \{\{(0, 0), (x, 0), (0, x)\} : 0 \leq x \leq 1\}$, then the mapping $d_s: X \times \mathcal{A} \longrightarrow \mathbb{R}^+$ given by the formula

$$d_s((z, 0), \{(0, 0), (x, 0), (0, x)\}) = (0, [z \cdot |z - x|^p]),$$

$$d_s((0, z), \{(0, 0), (x, 0), (0, x)\}) = ([z \cdot |z - x|^p], 0)$$

where $p \in \mathbb{N}$, is a point-set-cone metric with respect to d .

Remark 3.5. It is obvious from (PS2) that if $x \in A$, then $d_s(x, A) = \theta$. Therefore, from (PS1) we conclude the double implication: $d_s(x, A) = \theta \iff x \in A$.

Lemma 3.6. Let (X, d) be a cone metric space and let \mathcal{A} be a collection of nonempty subsets of X . Let H be a H -cone metric and d_s be a point-set-cone metric with respect to d . Then

$$\forall A, B \in \mathcal{A} \quad \forall a \in A \quad d_s(a, B) \preceq H(A, B).$$

Proof. Let $A, B \in \mathcal{A}$ and $a \in A$. Suppose, $\{c_n\}$ be a sequence in P° such that $c_n \rightarrow \theta$ as $n \rightarrow \infty$ and $\theta \ll c_n$ for all $n \in \mathbb{N}$. Then, by (H3) we have there exists $b \in B$ such that

$$d(a, b) \preceq H(A, B) + c_n \text{ for all } n \in \mathbb{N}.$$

By (PS2) we have $d_s(a, B) \preceq d(a, b)$, so by the above inequality we obtain $d_s(a, B) \preceq H(A, B) + c_n$ for all $n \in \mathbb{N}$, i.e., $H(A, B) + c_n - d_s(a, B) \in P$ for all $n \in \mathbb{N}$. Since P is closed, by choice of the sequence $\{c_n\}$ we have $H(A, B) - d_s(a, B) \in P$, i.e., $d_s(a, B) \preceq H(A, B)$. \square

Let (X, d) be a cone metric space and \mathcal{A} be a nonempty collection of nonempty subsets of X . In further discussion, $H: \mathcal{A} \times \mathcal{A} \rightarrow E$ will represent the H -cone metric and $d_s: X \times \mathcal{A} \rightarrow E$ will represent the point-set-cone metric with respect to d .

Now we can define various set-valued Prešić type contractions in cone metric spaces.

Let (X, d) be a cone metric space, k a positive integer, \mathcal{A} a nonempty collection of nonempty closed subsets of X and let $f: X^k \rightarrow \mathcal{A}$ be a mapping. Then, f is said to be Lipschitzian on X if there exist nonnegative constants α_i such that

$$H(f(x_0, x_1, \dots, x_{k-1}), f(x_1, x_2, \dots, x_k)) \preceq \sum_{i=1}^k \alpha_i d(x_{i-1}, x_i), \quad (3.1)$$

for all $x_0, x_1, \dots, x_k \in X$. If $\sum_{i=1}^k \alpha_i < 1$, then the mapping f is said to be a set-valued Prešić type contractions on X .

The mapping f is called a set-valued Prešić-Kannan type contraction on X if,

$$H(f(x_0, \dots, x_{k-1}), f(x_1, \dots, x_k)) \preceq a \sum_{i=0}^k d_s(x_i, f(x_i, \dots, x_i)) \quad (3.2)$$

for all $x_0, x_1, \dots, x_k \in X$, where the real constant a is such that $0 \leq ak(k+1) < 1$.

The mapping f is called a set-valued Prešić-Reich type contraction on X if,

$$\begin{aligned} H(f(x_0, \dots, x_{k-1}), f(x_1, \dots, x_k)) &\preceq \sum_{i=1}^k \alpha_i d(x_{i-1}, x_i) \\ &+ \sum_{i=0}^k \beta_i d_s(x_i, f(x_i, \dots, x_i)), \end{aligned} \quad (3.3)$$

for all $x_0, x_1, \dots, x_k \in X$, where α_i, β_i are nonnegative constants such that

$$\sum_{i=1}^k \alpha_i + k \sum_{i=0}^k \beta_i < 1. \quad (3.4)$$

We denote the set of all fixed points of f by $\text{Fix}f$ and

$$\text{Fix}f = \{x \in X : x \in f(x, \dots, x)\}.$$

The following theorem is the main result of this paper.

Theorem 3.1. *Let (X, d) be a complete cone metric space, k a positive integer and \mathcal{A} be a nonempty collection of nonempty closed subsets of X . If $f: X^k \rightarrow \mathcal{A}$ be a set-valued Prešić-Reich type contraction, then $\text{Fix}f \neq \emptyset$.*

Proof. Let $\{c_n\}$ be an arbitrary sequence in E which satisfies $\theta \ll c_n$ for all $n \in \mathbb{N}$. Let x_0 be an arbitrary point of X . Because $f(x_0, \dots, x_0) \in \mathcal{A}$, let $x_1 \in f(x_0, \dots, x_0)$. From (H3) there exists $x_2 \in f(x_1, \dots, x_1)$ such that

$$d(x_1, x_2) \preceq H(f(x_0, \dots, x_0), f(x_1, \dots, x_1)) + c_1.$$

Similarly, there exists $x_3 \in f(x_2, \dots, x_2)$ such that

$$d(x_2, x_3) \preceq H(f(x_1, \dots, x_1), f(x_2, \dots, x_2)) + c_2.$$

Continuing this procedure we obtain $x_{n+1} \in f(x_n, \dots, x_n)$ and

$$d(x_n, x_{n+1}) \preceq H(f(x_{n-1}, \dots, x_{n-1}), f(x_n, \dots, x_n)) + c_n \quad (3.5)$$

for all $n \in \mathbb{N}$.

As H is a metric on $N(X)$, for any $n \in \mathbb{N}$ it follows from (3.5) that

$$\begin{aligned} d(x_n, x_{n+1}) &\preceq H(f(x_{n-1}, \dots, x_{n-1}), f(x_n, \dots, x_n)) + c_n \\ &\preceq H(f(x_{n-1}, \dots, x_{n-1}), f(x_{n-1}, \dots, x_{n-1}, x_n)) \\ &\quad + H(f(x_{n-1}, \dots, x_{n-1}, x_n), f(x_{n-1}, \dots, x_{n-1}, x_n, x_n)) \\ &\quad + \dots + H(f(x_{n-1}, x_n, \dots, x_n), f(x_n, \dots, x_n)) + c_n. \end{aligned}$$

Since f is a set-valued Prešić-Reich type contraction, it follows from the above inequality that

$$\begin{aligned} d(x_n, x_{n+1}) &\preceq \alpha_k d(x_{n-1}, x_n) + \beta_0 d_s(x_{n-1}, f(x_{n-1}, \dots, x_{n-1})) + \dots \\ &\quad + \beta_{k-1} d_s(x_{n-1}, f(x_{n-1}, \dots, x_{n-1})) + \beta_k d_s(x_n, f(x_n, \dots, x_n)) \\ &\quad + \alpha_{k-1} d(x_{n-1}, x_n) + \beta_0 d_s(x_{n-1}, f(x_{n-1}, \dots, x_{n-1})) + \dots \\ &\quad + \beta_{k-1} d_s(x_n, f(x_n, \dots, x_n)) + \beta_k d_s(x_n, f(x_n, \dots, x_n)) \\ &\quad + \dots + \alpha_1 d(x_{n-1}, x_n) + \beta_0 d_s(x_{n-1}, f(x_{n-1}, \dots, x_{n-1})) \\ &\quad + \beta_1 d_s(x_n, f(x_n, \dots, x_n)) + \dots + \beta_k d_s(x_n, f(x_n, \dots, x_n)) \\ &\quad + c_n. \end{aligned}$$

Since $x_n \in f(x_{n-1}, \dots, x_{n-1})$ for all $n \in \mathbb{N}$, it follows from the definition of point-set-cone metric and the above inequality that

$$\begin{aligned} d(x_n, x_{n+1}) &\preceq \left[\sum_{i=1}^k \alpha_i \right] d(x_{n-1}, x_n) + \beta_0 d(x_{n-1}, x_n) + \dots \\ &\quad + \beta_{k-1} d(x_{n-1}, x_n) + \beta_k d(x_n, x_{n+1}) + \beta_0 d(x_{n-1}, x_n) + \dots \\ &\quad + \beta_{k-1} d(x_n, x_{n+1}) + \beta_k d(x_n, x_{n+1}) + \dots + \beta_0 d(x_{n-1}, x_n) \\ &\quad + \beta_1 d(x_n, x_{n+1}) + \dots + \beta_k d(x_n, x_{n+1}) + c_n. \end{aligned}$$

Rearranging the terms in the above expression, we obtain

$$d(x_n, x_{n+1}) \preceq \left[\sum_{i=1}^k \alpha_i + \sum_{i=0}^{k-1} (k-i)\beta_i \right] d(x_{n-1}, x_n) + \left[\sum_{i=1}^k i\beta_i \right] d(x_n, x_{n+1}) + c_n.$$

Thus, we have

$$d(x_n, x_{n+1}) \preceq \frac{\sum_{i=1}^k \alpha_i + \sum_{i=0}^k (k-i)\beta_i}{1 - \sum_{i=0}^k i\beta_i} d(x_{n-1}, x_n) + \frac{1}{1 - \sum_{i=0}^k i\beta_i} c_n. \quad (3.6)$$

For simplicity, set $A = \sum_{i=1}^k \alpha_i$, $B = k \sum_{i=0}^k \beta_i$, $C = \sum_{i=0}^k i\beta_i$ and $\lambda = \frac{A+B-C}{1-C}$, then in view of (3.4) we have,

$$A + B = \sum_{i=1}^k \alpha_i + k \sum_{i=0}^k \beta_i < 1, \quad C < 1, \text{ also } C \leq B,$$

and so, $0 \leq \lambda < 1$. Thus, from (3.6) it follows that

$$d(x_n, x_{n+1}) \preceq \lambda d(x_{n-1}, x_n) + \frac{c_n}{1-C} \text{ for all } n \in \mathbb{N}. \quad (3.7)$$

From the successive applications of the inequality (3.7) we obtain

$$\begin{aligned} d(x_n, x_{n+1}) &\preceq \lambda d(x_{n-1}, x_n) + \frac{c_n}{1-C} \\ &\preceq \lambda \left[\lambda d(x_{n-2}, x_{n-1}) + \frac{c_{n-1}}{1-C} \right] + \frac{c_n}{1-C} \\ &= \lambda^2 d(x_{n-2}, x_{n-1}) + \lambda \frac{c_{n-1}}{1-C} + \frac{c_n}{1-C} \\ &\preceq \lambda^2 \left[\lambda d(x_{n-3}, x_{n-2}) + \frac{c_{n-2}}{1-C} \right] + \lambda \frac{c_{n-1}}{1-C} + \frac{c_n}{1-C} \\ &= \lambda^3 d(x_{n-3}, x_{n-2}) + \lambda^2 \frac{c_{n-2}}{1-C} + \lambda \frac{c_{n-1}}{1-C} + \frac{c_n}{1-C}, \end{aligned}$$

which yields

$$d(x_n, x_{n+1}) \preceq \lambda^n d(x_0, x_1) + \frac{1}{1-C} \sum_{i=0}^{n-1} \lambda^i c_{n-i}.$$

Let $\omega \in P^\circ$, i.e., $\omega \in E$, $\theta \ll \omega$ be given. Since the sequence $\{c_n\}$ was arbitrary, choose c_n such that $\theta \ll c_n \ll \lambda^n \omega$ for all $n \in \mathbb{N}$. Therefore, it follows from the above inequality that

$$d(x_n, x_{n+1}) \ll \lambda^n d(x_0, x_1) + \frac{n\lambda^n}{1-C} \omega. \quad (3.8)$$

Let $n, m \in \mathbb{N}$ be such that $m > n$, then using inequality (3.8) we obtain

$$\begin{aligned} d(x_n, x_m) &\preceq d(x_n, x_{n+1}) + d(x_{n+1}, x_{n+2}) + \cdots + d(x_{m-1}, x_m) \\ &= \sum_{j=n}^{m-1} d(x_j, x_{j+1}) \\ &\ll \sum_{j=n}^{m-1} \left[\lambda^j d(x_0, x_1) + \frac{j\lambda^j}{1-C} \omega \right] \\ &= d(x_0, x_1) \sum_{j=n}^{m-1} \lambda^j + \frac{\omega}{1-C} \sum_{j=n}^{m-1} j\lambda^j. \end{aligned}$$

Since $0 \leq \lambda < 1$, therefore both the series $\sum_{n=1}^{\infty} \lambda^n$ and $\sum_{n=1}^{\infty} n\lambda^n$ are convergent series of nonnegative terms, and so, we have $\sum_{j=n}^{m-1} \lambda^j \rightarrow 0$ and $\sum_{j=n}^{m-1} j\lambda^j \rightarrow 0$ as $n \rightarrow \infty$. Therefore, the quantity on the right of the above inequality must tends to θ as $n \rightarrow \infty$. Now, using Lemma 2.3 and the last inequality we obtain, for each $c \in P^\circ$ there exists $n_0 \in \mathbb{N}$ such that $d(x_n, x_m) \ll c$ for all $n > n_0$. Therefore, $\{x_n\}$ is a Cauchy sequence.

By completeness of X , there exists $x^* \in X$ such that $x_n \rightarrow x^*$ as $n \rightarrow \infty$. We shall show that x^* is a fixed point of f . Using similar calculations to the previous one we obtain

$$\begin{aligned} & H(f(x_n, \dots, x_n), f(x^*, \dots, x^*)) \\ & \preceq Ad(x_n, x^*) + (B - C)d_s(x_n, f(x_n, \dots, x_n)) + Cd_s(x^*, f(x^*, \dots, x^*)) \end{aligned}$$

which with the fact $x_{n+1} \in f(x_n, \dots, x_n)$ and the definition of point-set-cone metric gives

$$\begin{aligned} H(f(x_n, \dots, x_n), f(x^*, \dots, x^*)) & \preceq Ad(x_n, x^*) + (B - C)d_s(x_n, x_{n+1}) \\ & \quad + Cd_s(x^*, f(x^*, \dots, x^*)). \end{aligned} \quad (3.9)$$

Suppose $c \in P^\circ$ be given, then since $x_{n+1} \in f(x_n, \dots, x_n)$, by (H3) for all $n \in \mathbb{N}$, there exists $y_n \in f(x^*, \dots, x^*)$ such that

$$d(x_{n+1}, y_n) \preceq H(f(x_n, \dots, x_n), f(x^*, \dots, x^*)) + c'_n, \quad (3.10)$$

where $\{c'_n\}$ is a sequence in P° such that $c'_n \ll \frac{(1-C)c}{4}$ for all $n \in \mathbb{N}$. Again, since $y_n \in f(x^*, \dots, x^*)$ we have

$$d_s(x^*, f(x^*, \dots, x^*)) \preceq d(x^*, y_n) \preceq d(x^*, x_{n+1}) + d(x_{n+1}, y_n)$$

which with (3.9) and (3.10) gives

$$\begin{aligned} d_s(x^*, f(x^*, \dots, x^*)) & \preceq d(x^*, x_{n+1}) + Ad(x_n, x^*) + (B - C)d(x_n, x_{n+1}) \\ & \quad + Cd_s(x^*, f(x^*, \dots, x^*)) + c'_n. \end{aligned}$$

Since $x_n \rightarrow x^*$ as $n \rightarrow \infty$ and $c'_n \ll \frac{(1-C)c}{4}$ for all $n \in \mathbb{N}$, we can choose $n_1 \in \mathbb{N}$ such that $d(x^*, x_{n+1}) \ll \frac{(1-C)c}{4}$, $d(x_n, x^*) \ll \frac{(1-C)c}{4A}$ and $d(x_n, x_{n+1}) \ll \frac{(1-C)c}{4(B-C)}$ for all $n > n_1$. Therefore, the above inequality yields

$$d_s(x^*, f(x^*, \dots, x^*)) \ll c \text{ for all } n > n_1.$$

Therefore, it follows from Lemma 2.3 and the above inequality that

$$d_s(x^*, f(x^*, \dots, x^*)) = \theta.$$

Thus, $x^* \in f(x^*, \dots, x^*)$, i.e., x^* is a fixed point of f . \square

Taking $k = 1$ in the above theorem, we obtain the following fixed point theorem which generalize the result of Wardowski [16] without assuming the normality of the underlying cone.

Corollary 3.7. *Let (X, d) be a complete cone metric space and \mathcal{A} be a nonempty collection of nonempty closed subsets of X . If for a map $f: X \rightarrow \mathcal{A}$ there exist nonnegative constants α, β_0, β_1 such that $\alpha + \beta_0 + \beta_1 < 1$ and*

$$H(fx, fy) \preceq \alpha d(x, y) + \beta_0 d_s(x, fx) + \beta_1 d_s(y, fy)$$

for all $x, y \in X$, then $\text{Fix}f \neq \emptyset$.

Corollary 3.8. Let (X, d) be a complete cone metric space and \mathcal{A} be a nonempty collection of nonempty closed subsets of X . If for a map $f: X \rightarrow \mathcal{A}$ there exist nonnegative constants β_0, β_1 such that $\beta_0 + \beta_1 < 1$ and

$$H(fx, fy) \preceq \beta_0 d_s(x, fx) + \beta_1 d_s(y, fy)$$

for all $x, y \in X$, then $\text{Fix}f \neq \emptyset$.

Corollary 3.9. Let (X, d) be a complete cone metric space and \mathcal{A} be a nonempty collection of nonempty closed subsets of X . If for a map $f: X \rightarrow \mathcal{A}$ there exists $\alpha \in [0, 1)$ such that

$$H(fx, fy) \preceq \alpha d(x, y)$$

for all $x, y \in X$, then $\text{Fix}f \neq \emptyset$.

Corollary 3.10. Let (X, d) be a complete cone metric space, k a positive integer and \mathcal{A} be a nonempty collection of nonempty closed subsets of X . If $f: X^k \rightarrow \mathcal{A}$ be a set-valued Prešić-Kannan type contraction, then $\text{Fix}f \neq \emptyset$.

Proof. Taking $\alpha_i = 0$ for $i = 1, 2, \dots, k$ and $\beta_i = a$ (say) for $i = 0, 1, \dots, k$ in Theorem 3.1, we obtain the desired result. \square

Corollary 3.11. Let (X, d) be a complete cone metric space, k a positive integer and \mathcal{A} be a nonempty collection of nonempty closed subsets of X . If $f: X^k \rightarrow \mathcal{A}$ be a set-valued Prešić type contraction, then $\text{Fix}f \neq \emptyset$.

Proof. Taking $\beta_i = 0$ for $i = 0, 1, \dots, k$ in Theorem 3.1, we obtain the desired result. \square

Example 3.12. Let $X = [0, 1]$, $E = C_{\mathbb{R}}^1[0, 1]$ with the norm $\|\psi\| = \|\psi\|_{\infty} + \|\psi'\|_{\infty}$ and $P = \{\psi \in E: \psi(t) \geq 0, t \in [0, 1]\}$. Define $d: X \times X \rightarrow E$ by

$$d(x, y) = |x - y| \phi(t) \text{ for all } x, y \in X,$$

where $\phi(t) = e^t$, $t \in [0, 1]$. Then, (X, d) is a complete cone metric space. Let \mathcal{A} be the family of subsets of X of the form $\mathcal{A} = \{[0, x]: x \in X\} \cup \{\{x\}: x \in X\}$, and define the functions $H: \mathcal{A} \times \mathcal{A} \rightarrow E$ and $d_s: X \times \mathcal{A} \rightarrow E$ by

$$H(A, B) = \begin{cases} |x - y| \cdot e^t, & \text{for } A = [0, x], B = [0, y]; \\ |x - y| \cdot e^t, & \text{for } A = \{x\}, B = \{y\}; \\ \max\{y, |x - y|\} \cdot e^t, & \text{for } A = [0, x], B = \{y\}; \\ \max\{x, |x - y|\} \cdot e^t, & \text{for } A = \{x\}, B = [0, y] \end{cases}$$

and

$$d_s(x, A) = \min\{|x - a|: a \in A\} \cdot e^t, \quad t \in [0, 1] \text{ for all } x \in X.$$

Then, H is a H -cone metric and d_s is a point-set-cone metric with respect to d . For $k = 2$, define a mapping $f: X^2 \rightarrow \mathcal{A}$ as follows:

$$f(x, y) = \begin{cases} [0, \frac{1}{5}(x + y - 1)^2], & \text{if } x, y \in (\frac{1}{2}, 1]; \\ \{0\}, & \text{otherwise.} \end{cases}$$

Now, by some routine calculations one can see that the mapping f is a set-valued Prešić-Reich type contraction on X^2 with $\alpha_1 = \alpha_2 = \frac{2}{5}$ and $\beta_1 = \beta_2 = \beta_3 = \frac{1}{36}$. All the conditions of Theorem 3.1 are satisfied and $0 \in \text{Fix}f$.

In the next theorem, we replace the completeness of cone metric space by an additional condition on the set-valued Prešić-Reich type contractions.

Theorem 3.2. Let (X, d) be a cone metric space, k a positive integer, \mathcal{A} a nonempty collection of nonempty closed subsets of X and $f: X^k \rightarrow \mathcal{A}$ be a set-valued Prešić-Reich type contraction. Suppose there exists $x^* \in X$ such that

$$d_s(x^*, f(x^*, \dots, x^*)) \preceq d_s(x, f(x, \dots, x)) \text{ for all } x \in X.$$

Then $\text{Fix}f \neq \emptyset$.

Proof. Let $D(x) = d_s(x, f(x, \dots, x))$ for all $x \in X$. Then by assumption we have

$$D(x^*) \preceq D(x) \text{ for all } x \in X. \quad (3.11)$$

If $x^* \in f(x^*, \dots, x^*)$, then $x^* \in \text{Fix}f$. Suppose $x^* \notin f(x^*, \dots, x^*)$, then $D(x^*) = d_s(x^*, f(x^*, \dots, x^*)) \neq \theta$. Let $x_0 = x^*$, then following similar arguments to those in Theorem 3.1, the sequence $\{x_n\}$, where $x_n \in f(x_{n-1}, \dots, x_{n-1})$ for all $n \in \mathbb{N}$ is a Cauchy sequence in X . Now, by Lemma 3.6, we have

$$\begin{aligned} D(x_n) &= d_s(x_n, f(x_n, \dots, x_n)) \\ &\preceq H(f(x_{n-1}, \dots, x_{n-1}), f(x_n, \dots, x_n)) \\ &\preceq H(f(x_{n-1}, \dots, x_{n-1}), f(x_{n-1}, \dots, x_{n-1}, x_n)) \\ &\quad + H(f(x_{n-1}, \dots, x_{n-1}, x_n), f(x_{n-1}, \dots, u, x_n, x_n)) \\ &\quad + \dots + H(f(x_{n-1}, x_n, \dots, x_n), f(x_n, \dots, x_n)) \\ &\preceq Ad(x_{n-1}, x_n) + (B - C)d_s(x_{n-1}, f(x_{n-1}, \dots, x_{n-1})) \\ &\quad + Cd_s(x_n, f(x_n, \dots, x_n)), \end{aligned}$$

where $A = \sum_{i=1}^k \alpha_i$, $B = k \sum_{i=0}^k \beta_i$ and $C = \sum_{i=0}^k i\beta_i$.

Since $x_n \in f(x_{n-1}, \dots, x_{n-1})$ for all $n \in \mathbb{N}$, by (PS2) we have

$$d_s(x_{n-1}, f(x_{n-1}, \dots, x_{n-1})) \preceq d(x_{n-1}, x_n) \text{ for all } n \in \mathbb{N}.$$

Therefore, it follows from the above inequality that

$$D(x_n) \preceq \frac{A + B - C}{1 - C} d(x_{n-1}, x_n) \text{ for all } n \in \mathbb{N}.$$

As, $A + B < 1$, $C \leq B$, and $\{x_n\}$ is a Cauchy sequence, for each $c \in P$ with

$\theta \ll c$ there exists $n_0 \in \mathbb{N}$ such that $d(x_{n-1}, x_n) \ll \frac{(1 - C)c}{A + B - C}$ for all $n > n_0$.

So, it follows from the above inequality that $D(x_n) \ll c$ for all $n > n_0$. Using the inequality (3.11) and the Remark 2.3 we have

$$D(x^*) \ll c \text{ for all } n \in \mathbb{N}.$$

Therefore, we must have $D(x^*) = \theta$, i.e., $d_s(x^*, f(x^*, \dots, x^*)) = \theta$, or, $x^* \in f(x^*, \dots, x^*)$. Thus $x^* \in \text{Fix}f$. \square

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